



Recent Advances in Re-Analysis Methods for NVH Including Shape and Topology Optimization

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Definitions / Motivation



Vibration Analysis is Computationally Intensive

Deterministic Design Optimization Requires MANY Vibration Analyses

Probabilistic Design Optimization Requires EVEN MORE Vibration Analyses



Observations

In Noise, Vibration and Harshness (NVH) :

- Physical partitioning (substructuring) is commonly used
- **FRF substructuring** for interfaces with **few** DOFs
- **Craig-Bampton (CMS) substructuring** for interfaces with **many** DOFs

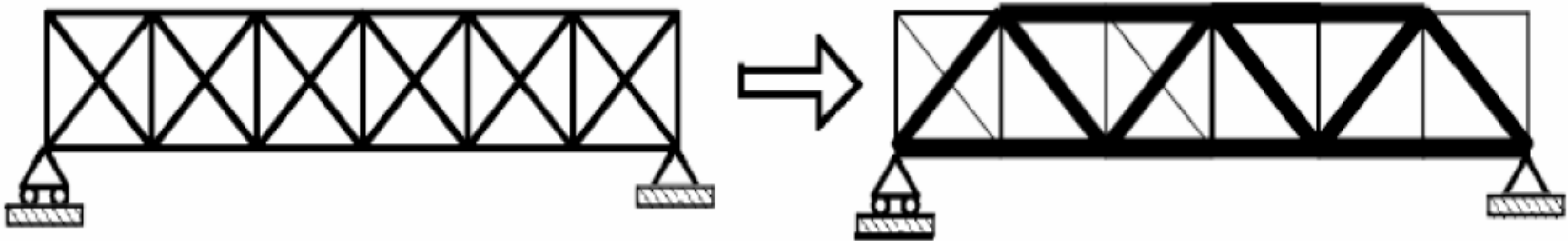
In design optimization :

- Changes can be global or **local**. The latter are common
- “**Gauge**” (e.g. thickness), **shape**, or **topology** changes

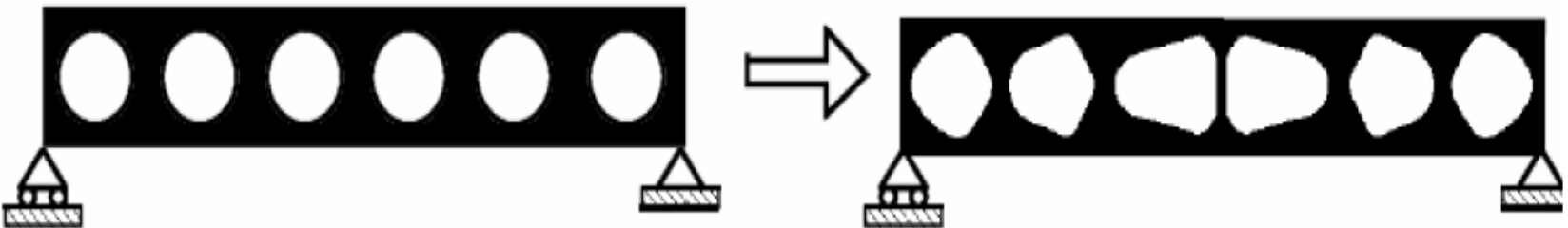
Classification of Optimization Methods



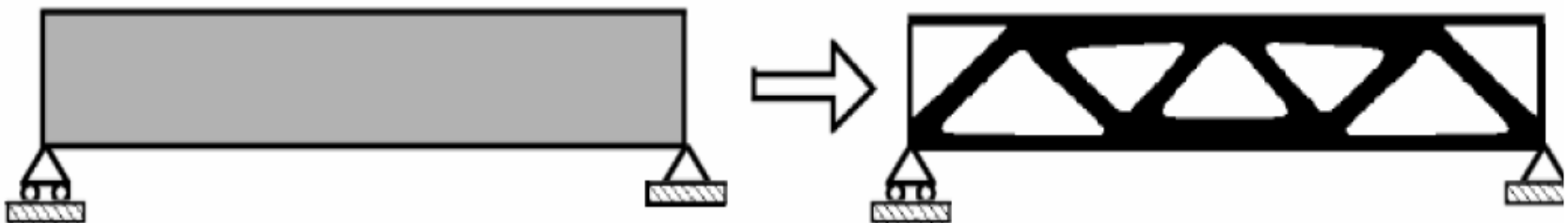
Gauge



Shape

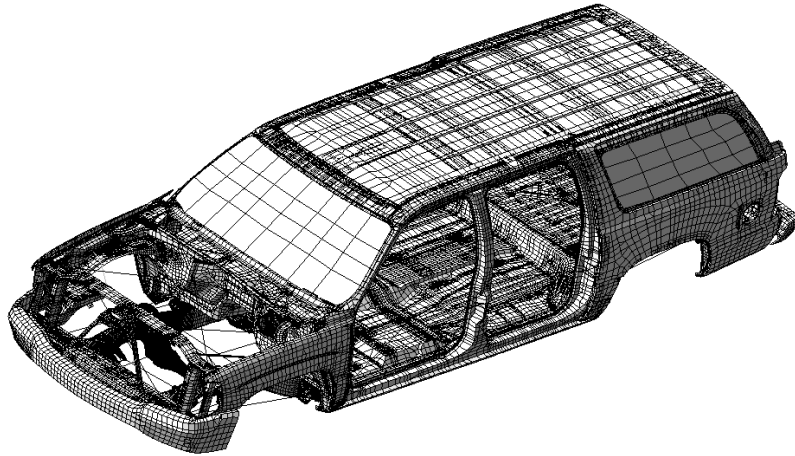


Topology



Reduced-Order Modeling (Modal Model)

“All-in-One” Approach



Re-analysis Methods

- CDH/VBA Method
- MCA Method
- PROM / MCA Method

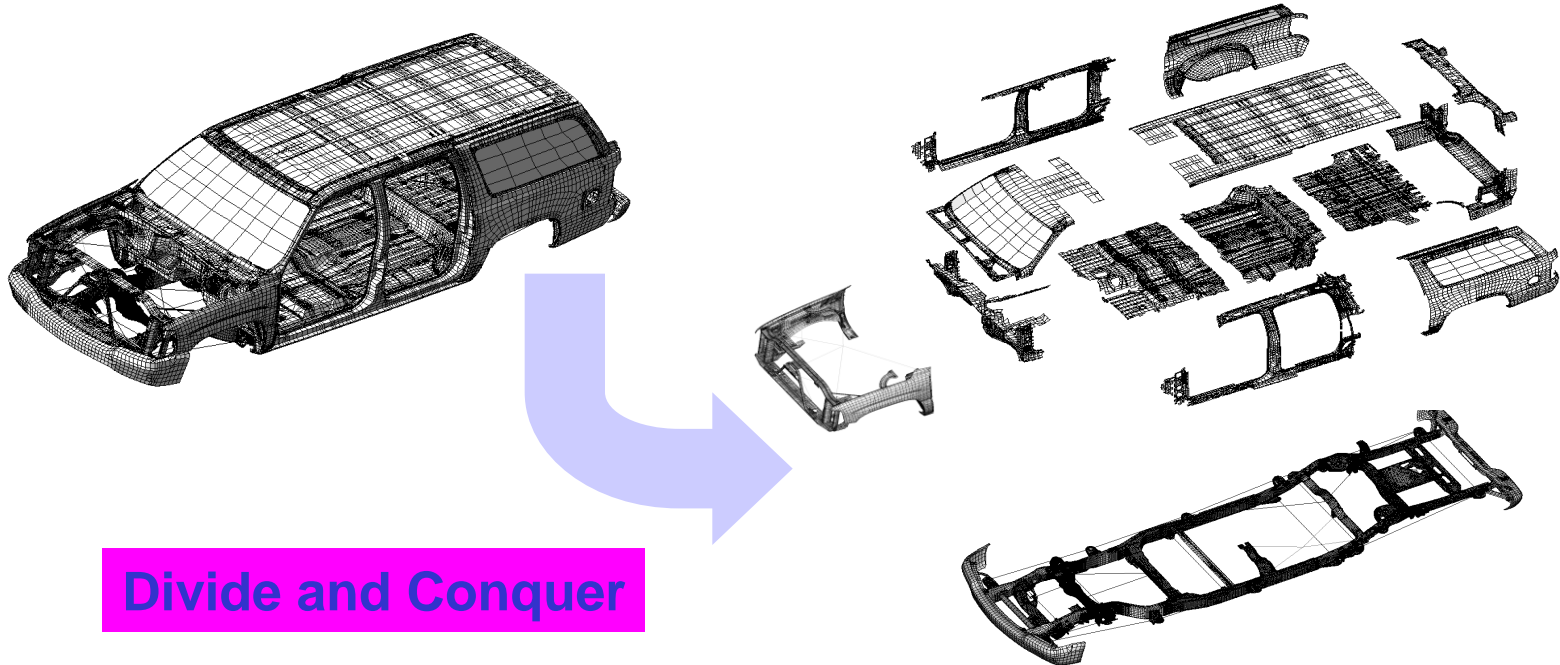
Modal Model:
$$[\Phi^T \mathbf{K} \Phi - \omega^2 \Phi^T \mathbf{M} \Phi] \mathbf{U} = \Phi^T \mathbf{F}$$

Practical Issues:

- Basis Φ must be recalculated for each new design
- Calculation of “triple” product $\Phi^T \mathbf{K} \Phi$ can be expensive

Reduced-Order Modeling (Modal Model)

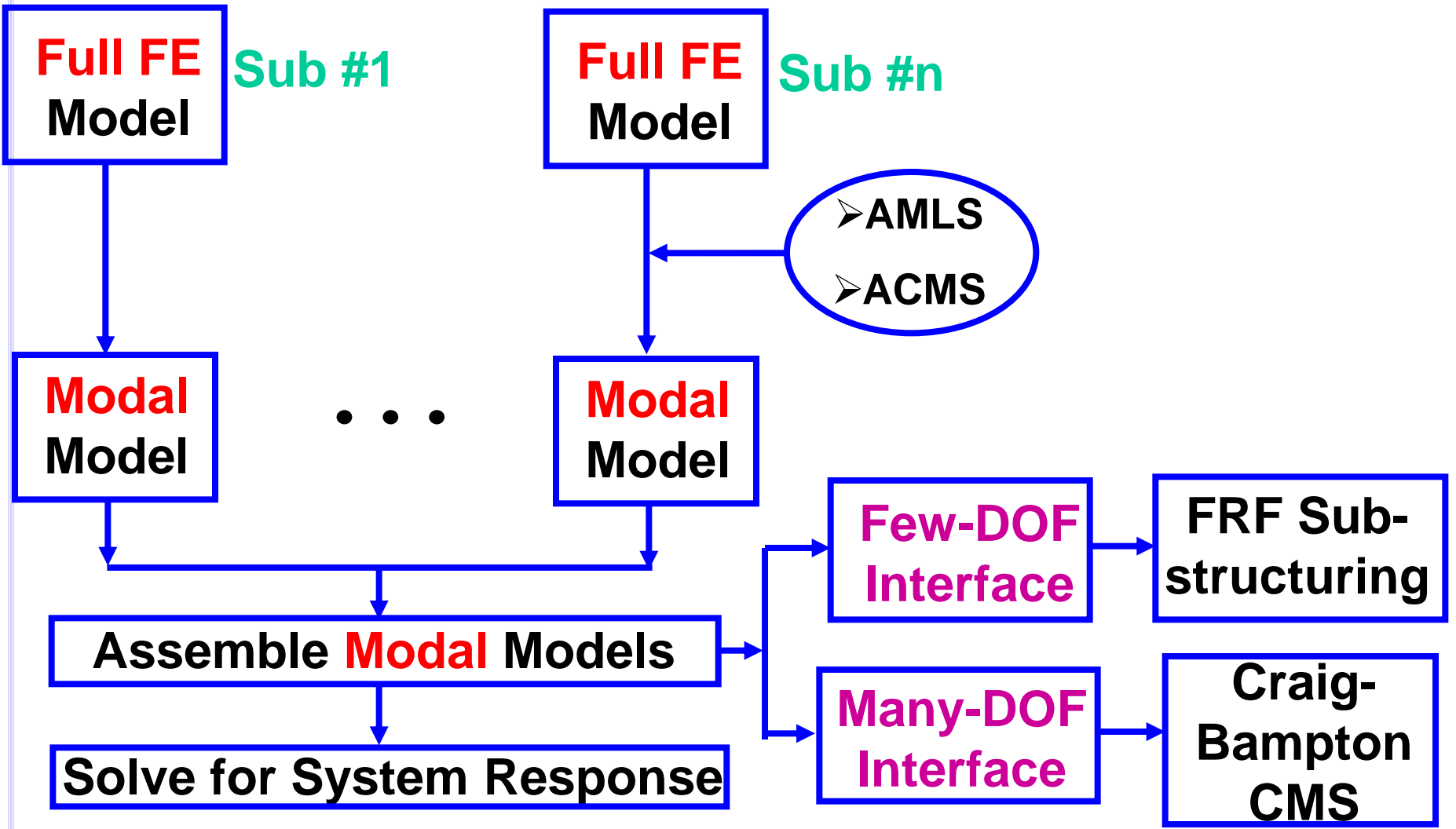
Substructuring Approach



Practical Issues:

- Basis Φ must be recalculated for each new design
- Calculation of “triple” product $\Phi^T \mathbf{K} \Phi$ can be expensive
- Interface matrices can be large in size

Substructuring Approach





Overview / Demonstration of Re-Analysis Methods

- **Basic Concept of Re-Analysis Methods**
- **Re-Analysis Methods for Shape Changes**
 - **Different Examples**
 - **Shape/Gauge Optimization (Car Example)**
- **Re-Analysis in Topology Optimization**
 - **Automotive Door Example**

Basic Concept of Re-Analysis Methods



Re-Analysis methods provide approximate eigenvalues and eigenvectors

Conventional Approach

Eigen-analysis of full matrices

$$eig(\mathbf{K}, \mathbf{M}) \Rightarrow \lambda, \Phi$$

Re-analysis Approach

1. Form reduced basis: \mathbf{P}

2. Project system matrices to reduced basis:

$$\mathbf{K}_R = \mathbf{P}^T \mathbf{K} \mathbf{P} \quad \mathbf{M}_R = \mathbf{P}^T \mathbf{M} \mathbf{P}$$

3. Eigen-analysis of reduced matrices:

$$eig(\mathbf{K}_R, \mathbf{M}_R) \Rightarrow \tilde{\lambda}^p, \Theta$$

4. Obtain approximate eigenvectors:

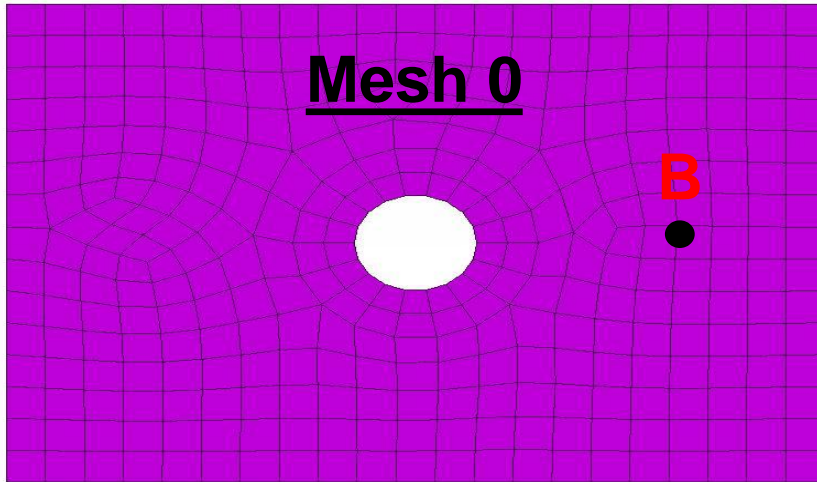
$$\tilde{\Phi} = \mathbf{P} \Theta$$

Re-Analysis methods (e.g. **CDH, PROM, MCA) are differentiated by definition of reduced basis \mathbf{P}**



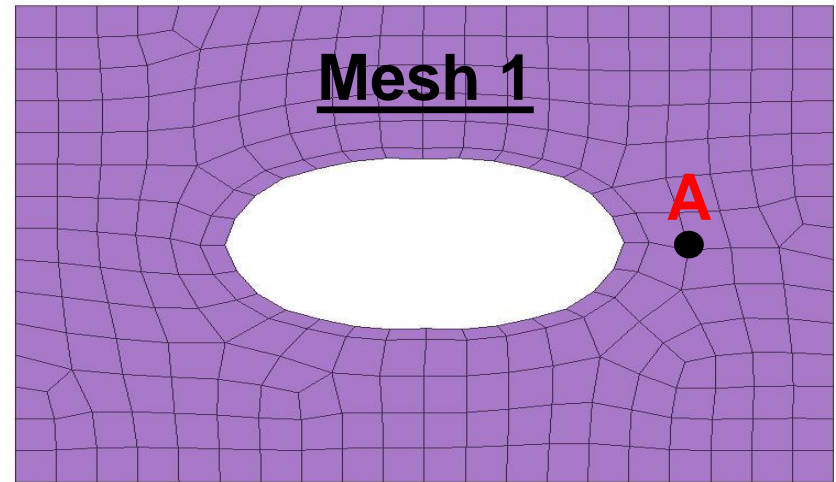
Re-Analysis Methods for Shape Changes

Major Challenge: Different mesh between baseline and modified designs



Mesh 0

B



Mesh 1

A

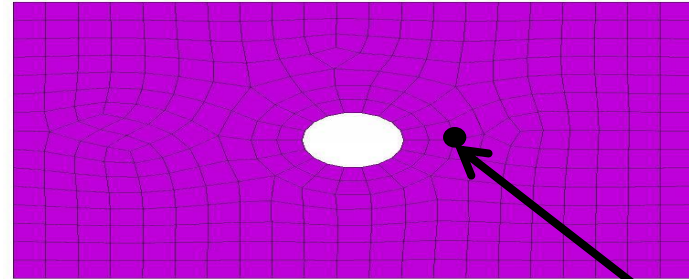
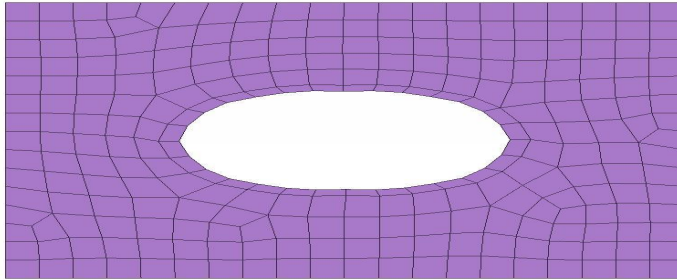
$$\Phi_0 \quad (n \times m)$$

$$\Phi_1 \quad (l \times m)$$

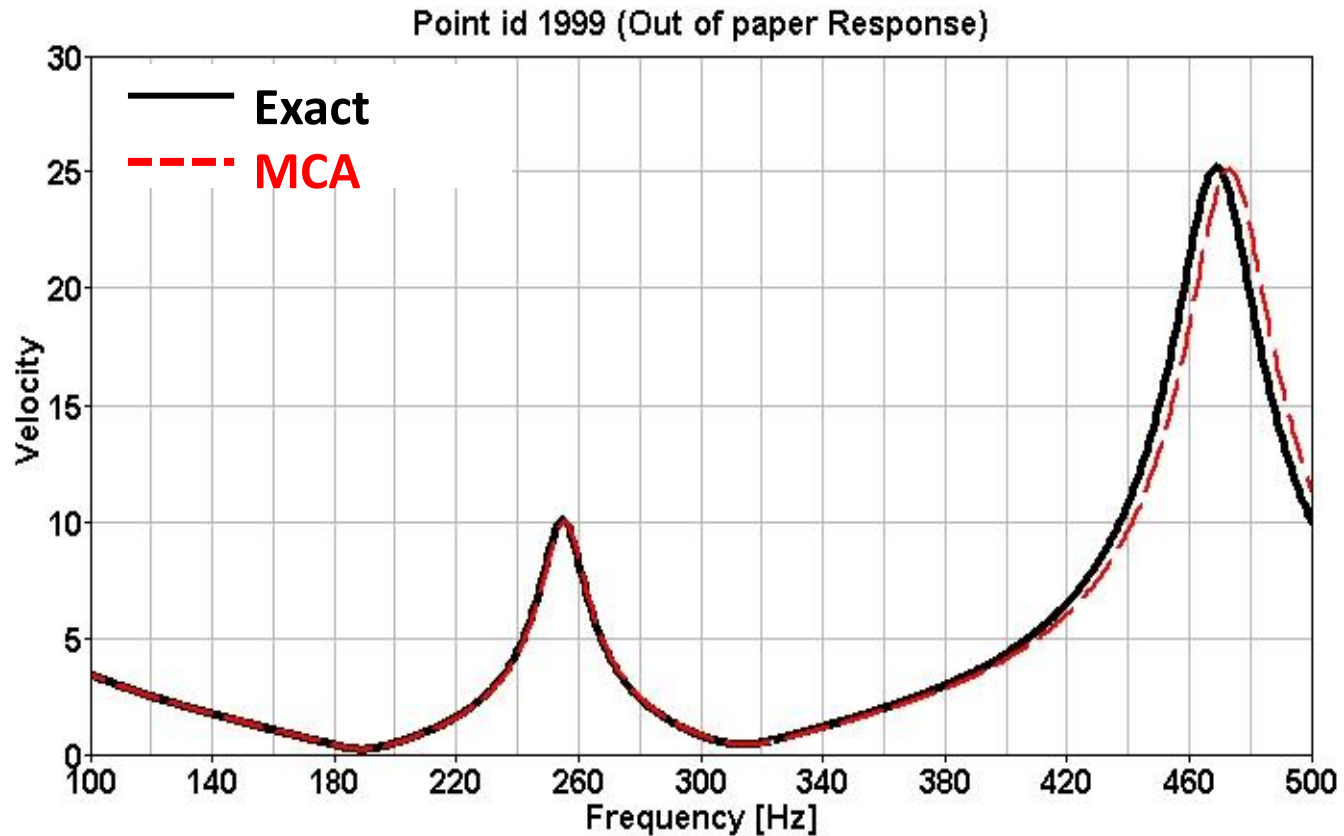
For each node **A** of FE mesh 1
 identify closest node **B** of ME mesh 0 $\Rightarrow \hat{\Phi}_1 \quad (l \times m)$

Use **MCA** starting with $\hat{\Phi}_1$ to
 estimate Φ_1

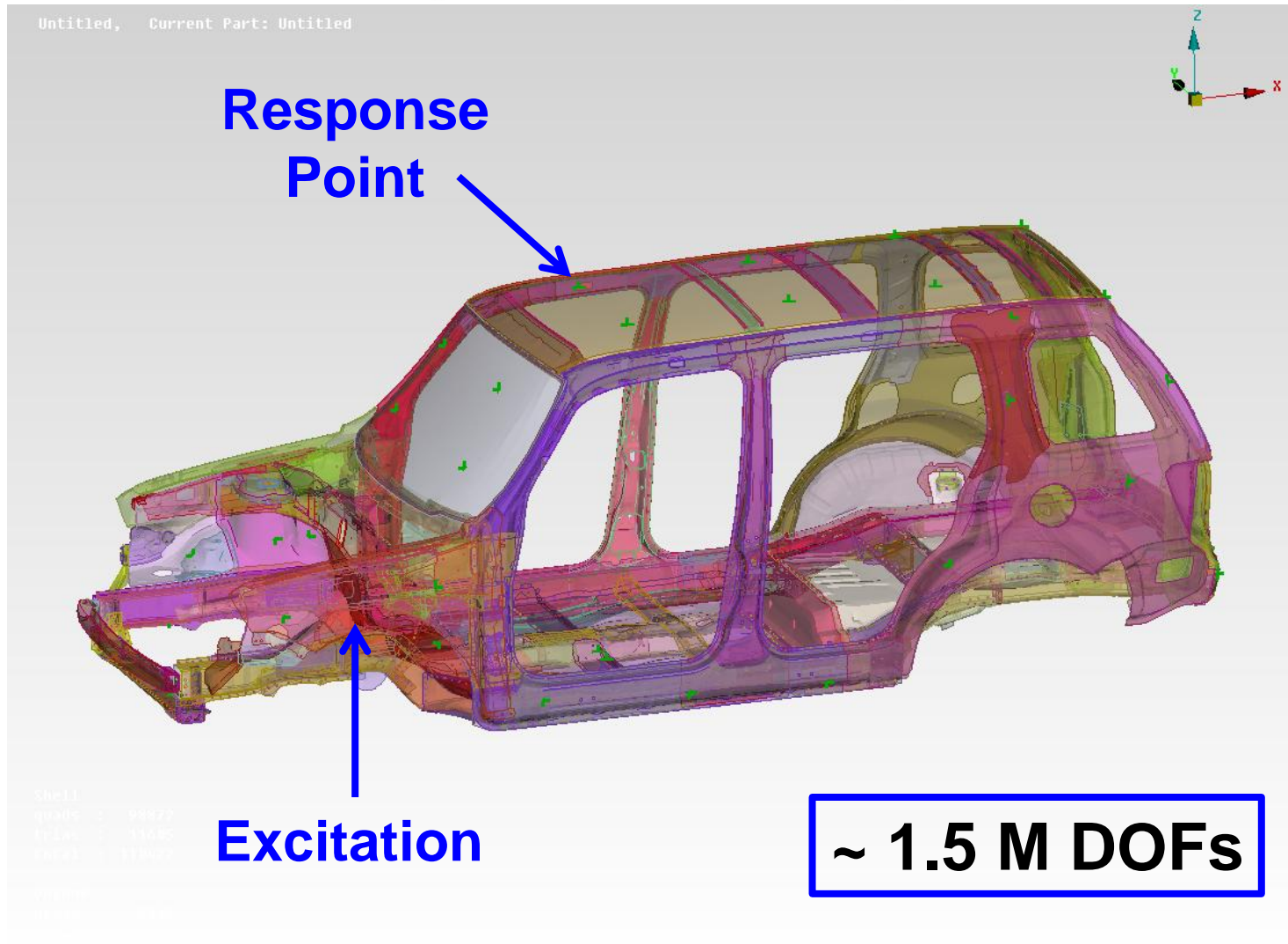
MCA for Shape Changes: Different DOFs



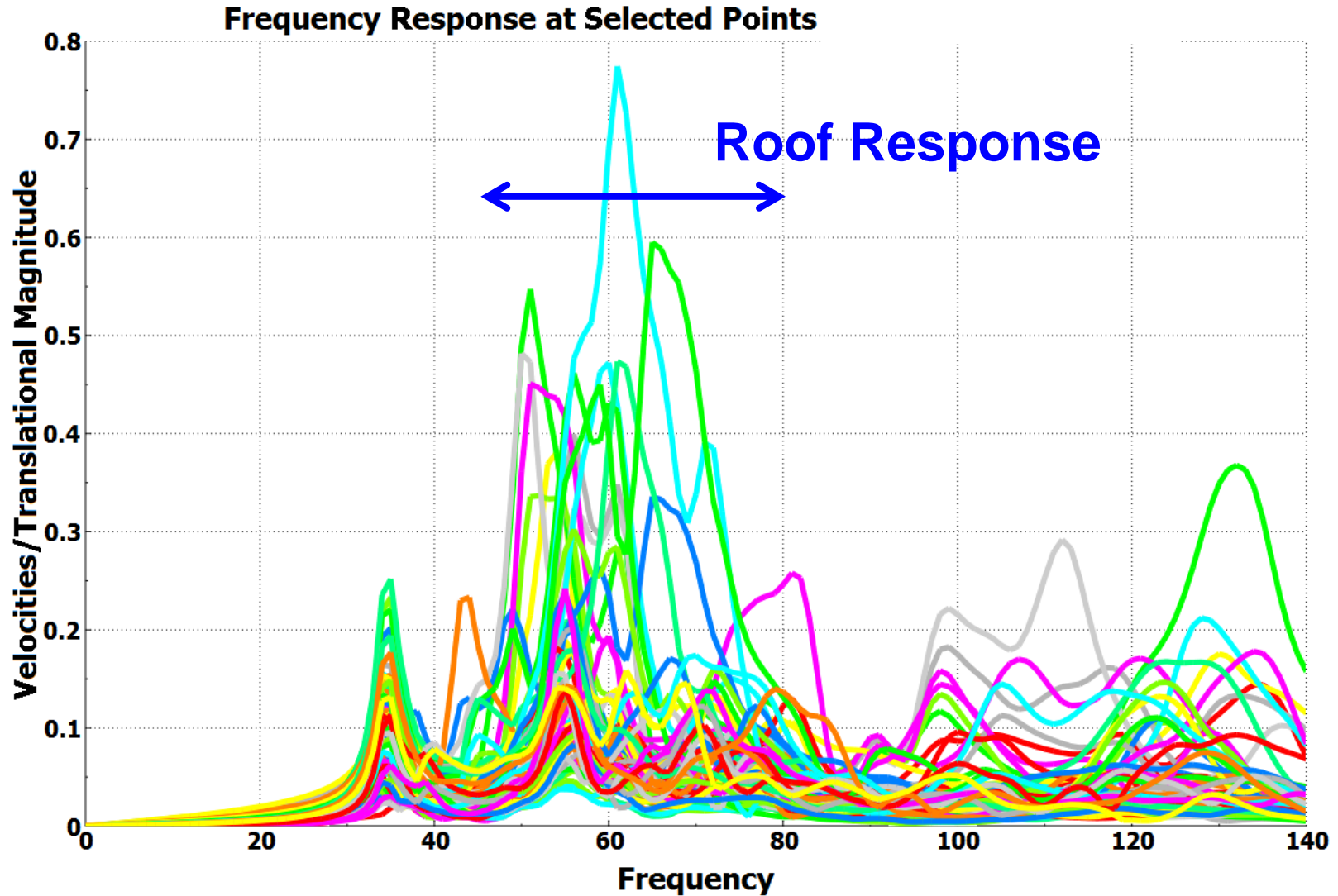
1999



Example of Shape / Gauge Optimization using MCA Re-Analysis



Example of Shape / Gauge Optimization using MCA Re-Analysis



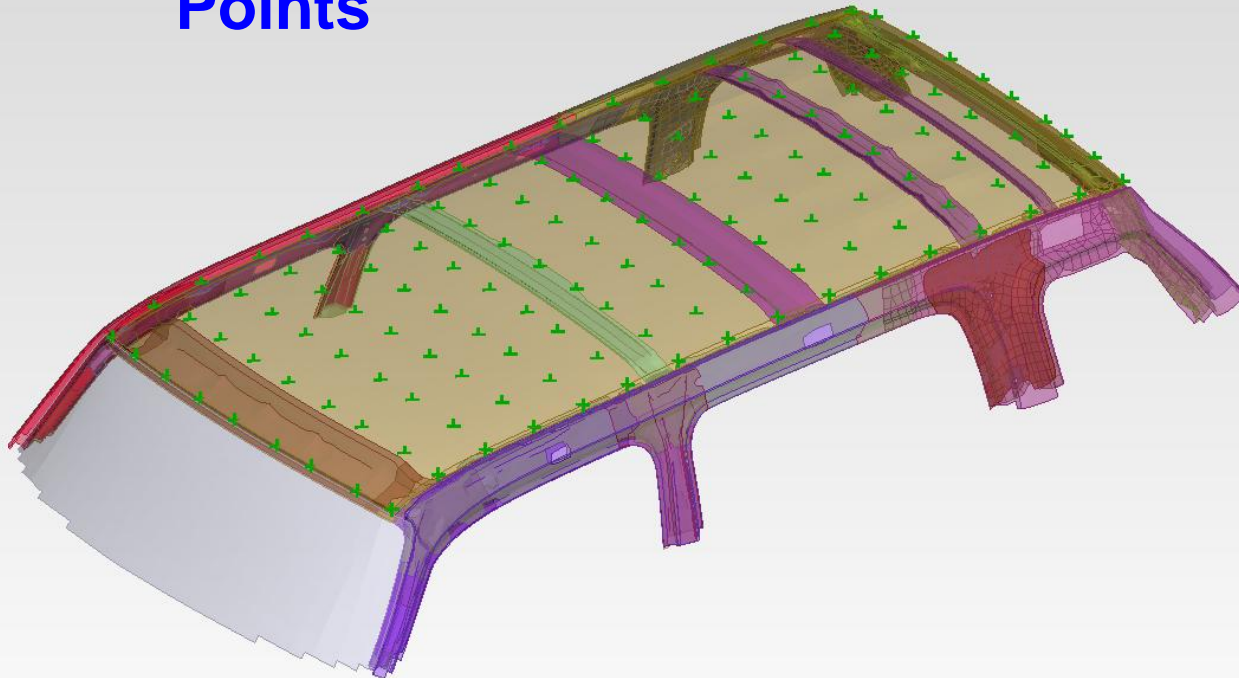
Example of Shape / Gauge Optimization using MCA Re-Analysis



Untitled, Current Part: Untitled



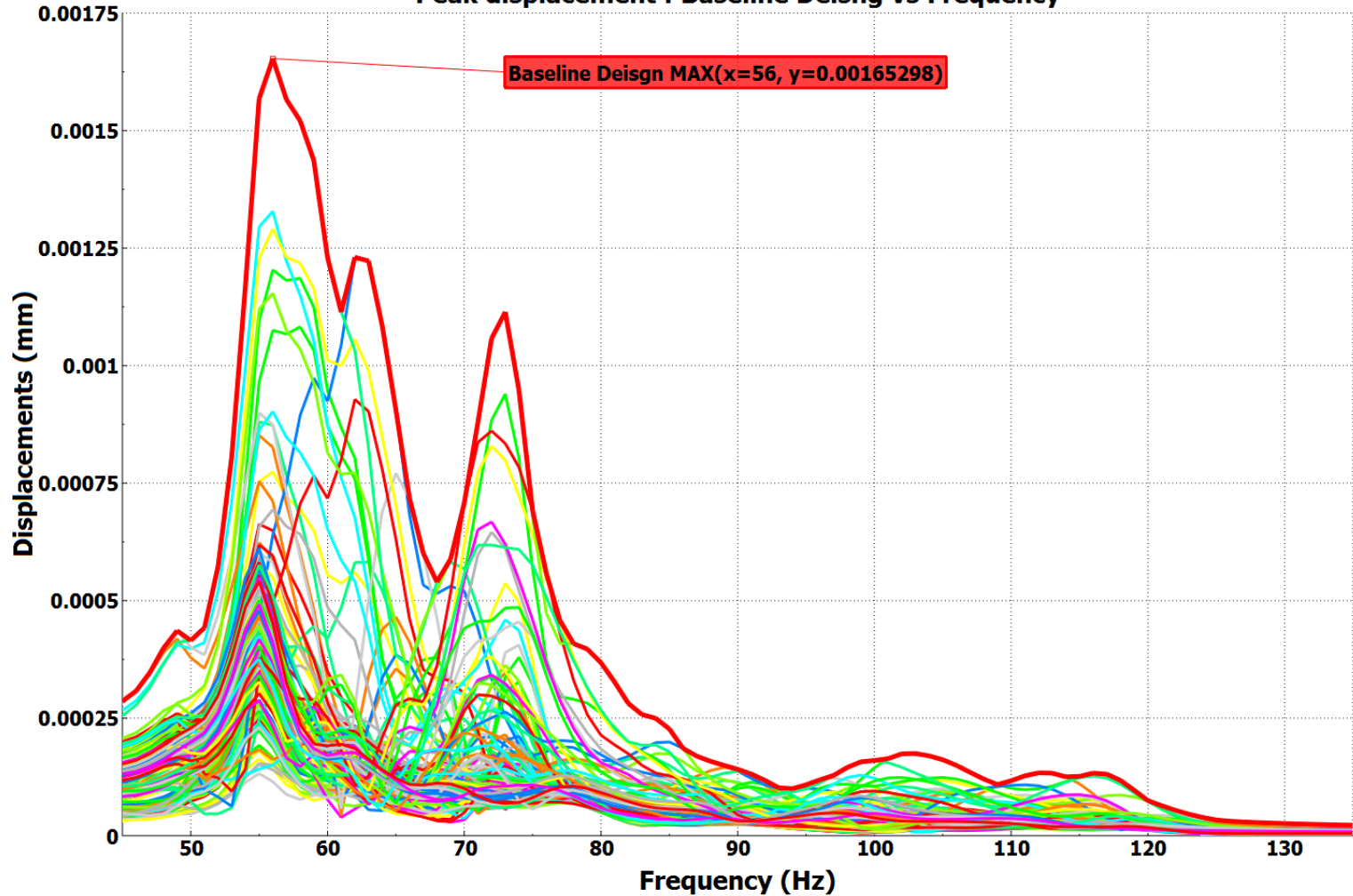
Roof Response Points





Example of Shape / Gauge Optimization using MCA Re-Analysis Roof Peak Response Envelope

Peak displacement : Baseline Deisgn vs Frequency



Design Variables

Morphing Variables



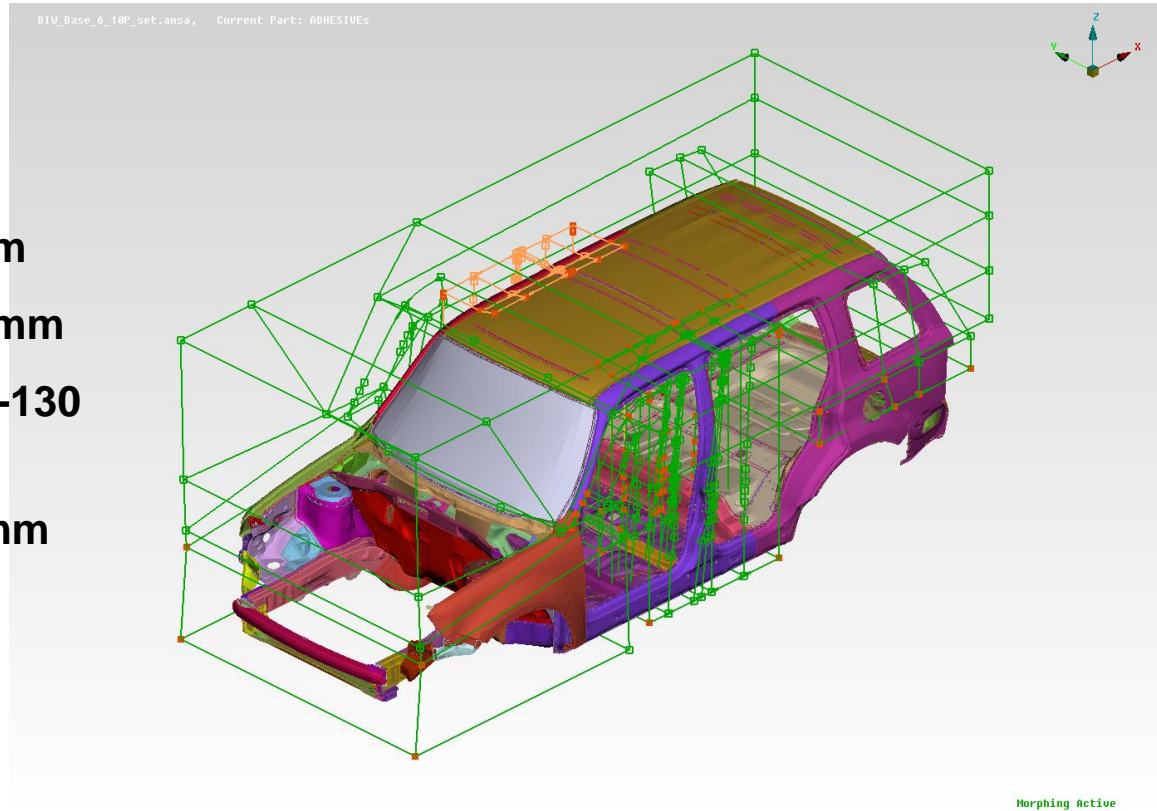
No.	Parameter	Baseline	Lower Bound (mm)	Upper Bound (mm)
1	BPillar_Width	0	-10	40
2	RR_Header_X_Position	0	-150	150
3	Windshield_Header_Position	0	-130	130
4	Roof_Height	0	-130	150
5	7850276_Cross Bow 1	0.75	0.4	2
6	7850263_Cross Bow Main	0.75	0.4	2
7	7824312_B-Pillar Inner RT Gauge	1.2	0.4	2
8	78502076_Roof Cross Bow 2	0.75	0.4	2
9	7824557_B-Pillar Inner RT Gauge	1.6	0.4	2
10	47071_Floor Cross Member Rea	1.4	0.4	2
11	7810628_Floor Seat Cross Member	0.75	0.4	2
12	92_Roof Cross Bow 3	0.75	0.4	2
13	7850202_Roof Gauge	0.79	0.4	2

Shape Design Variables



- B-Pillar Width = -10 to 40 mm**
- RR Header Pos = -150 to 150 mm**
- Windshield Header Position = -130 to +130 mm**
- Roof Height = -130 to + 150 mm**

**All values w.r.t.
baseline at zero**





Optimization Statement

Find $\mathbf{X} = [X_1 \quad X_2 \quad \dots \quad X_{13}]$

of Design Variables

of Roof Response Pts

to

$$\min_{\mathbf{X}} \left[\max_{i=1}^{145} (\text{Re } sp_i) \right]$$

NSGA II Optimizer

s. t. $Mass \leq Mass_{Nominal}$

where : $\text{Re } sp = |y(f)|$, $f \in \{45, 140\} \text{ Hz}$

Roof Displacement Magnitude



Approach

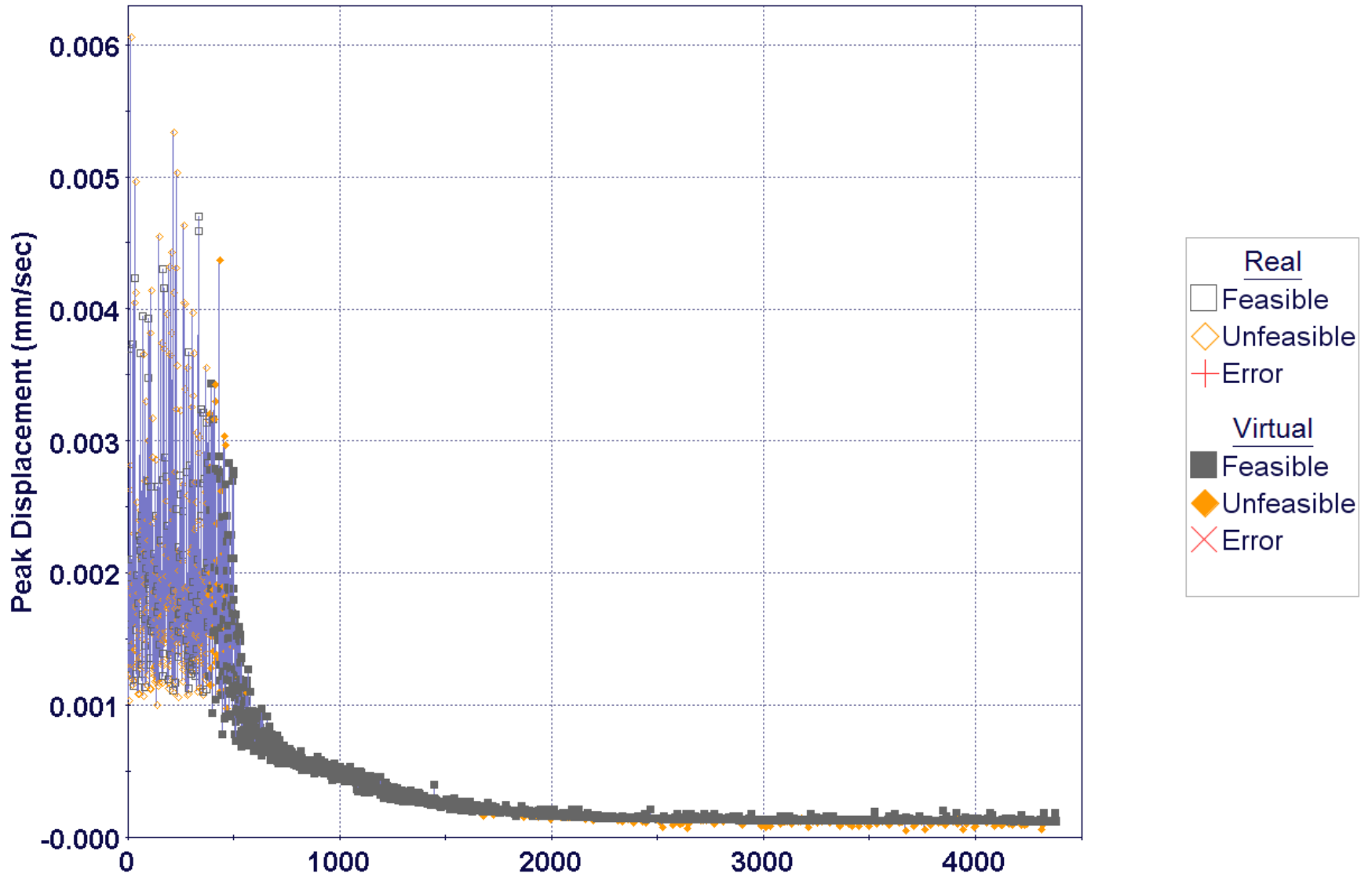
- Kriging Metamodel (RSM)
- Design of Experiments using incremental space filling algorithm

Design Pts	Average Error
40	53 %
80	35 %
120	26 %
160	31 %
200	18 %
375	10 %

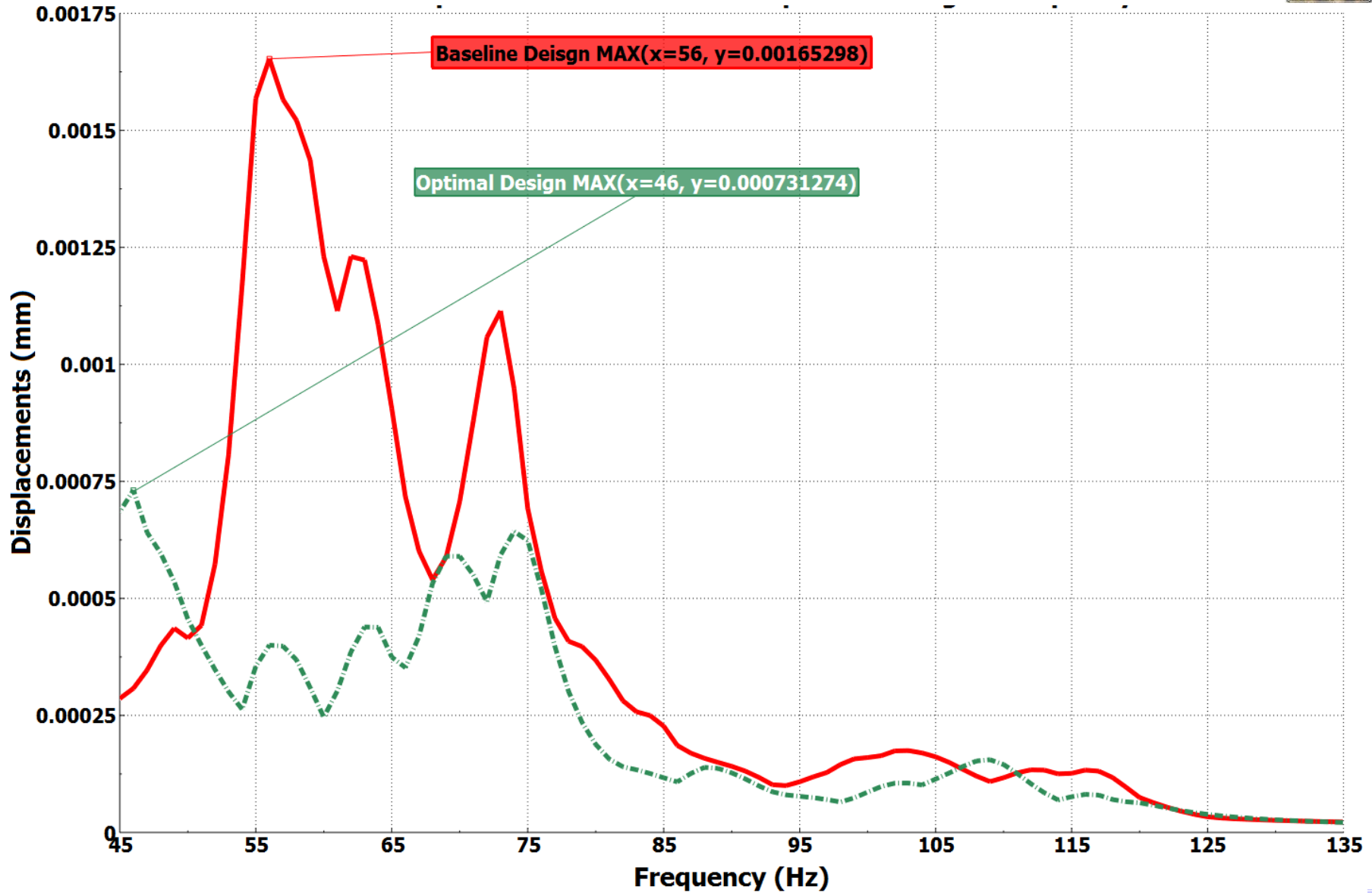
MCA Re-analysis <u>CPU Reduction</u> per Design Pt	3 min 21 sec
375 Designs	21.1 hrs

ModeFRONTIER
was used

Optimization History



Baseline and Optimal Designs

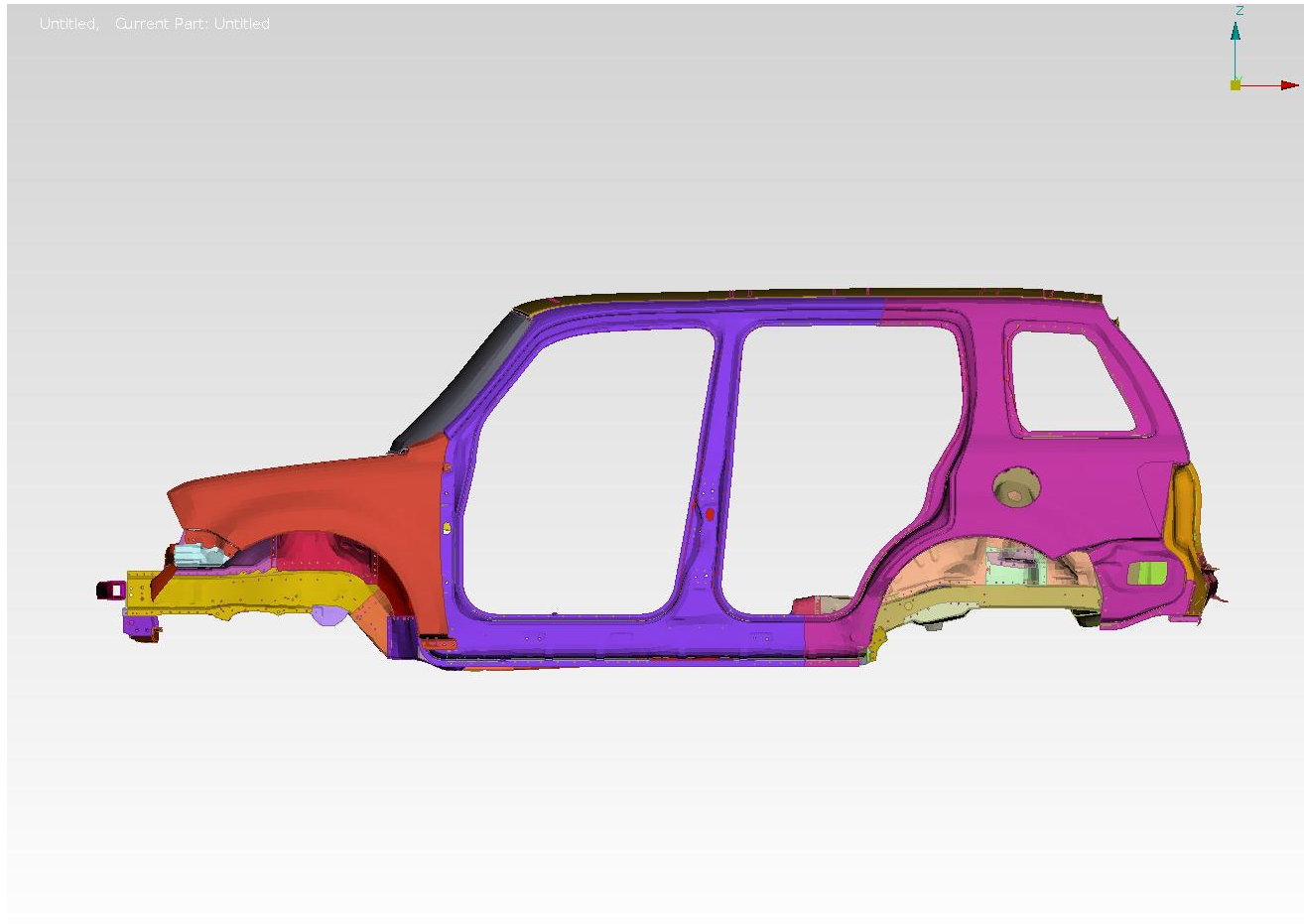


Baseline and Optimal Values

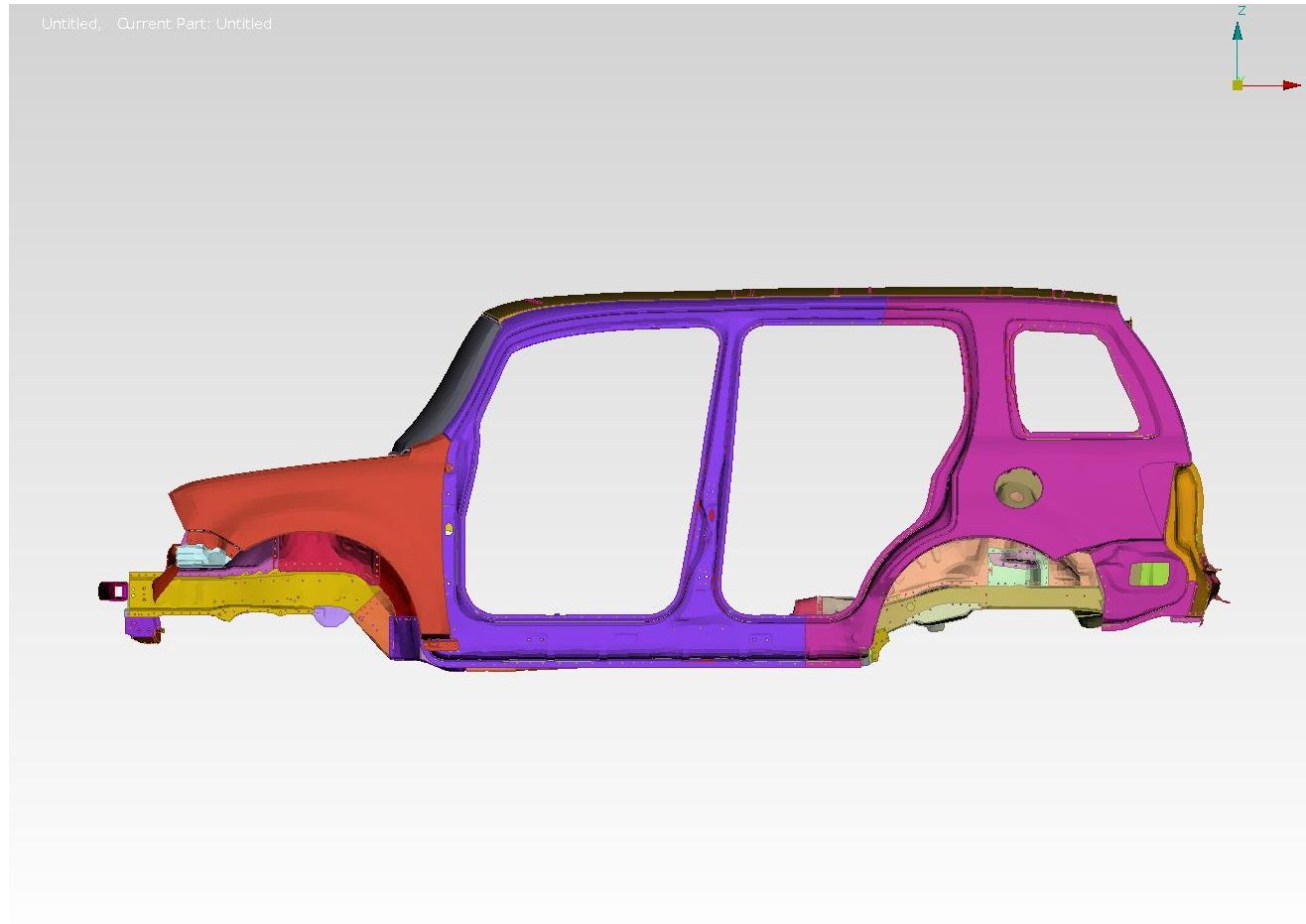


No.	Parameter Name	Baseline	Optimal	Lower Bound (mm)	Upper Bound (mm)
1	BPillar_Width	0	-9.92708	-10	40
2	RR Header X Position	0	54.24584	-150	150
3	Windshield Header Position	0	-129.999	-130	130
4	Roof Height	0	6.298661	-130	150
5	7850276 Cross Bow 1	0.75	0.732604	0.4	2
6	7850263 Cross Bow Main	0.75	1.999987	0.4	2
7	7824312_ B-Pillar Inner RT Gauge	1.2	0.517935	0.4	2
8	78502076_Roof Cross Bow 2	0.75	1.165611	0.4	2
9	7824557_ B-Pillar Inner RT Gauge	1.6	0.400019	0.4	2
10	47071 Floor Cross Member Rea	1.4	1.387041	0.4	2
11	7810628 Floor Seat Cross Member	0.75	1.079494	0.4	2
12	92 Roof Cross Bow 3	0.75	1.999551	0.4	2
13	7850202 Roof Gauge	0.79	1.999617	0.4	2

Baseline Design



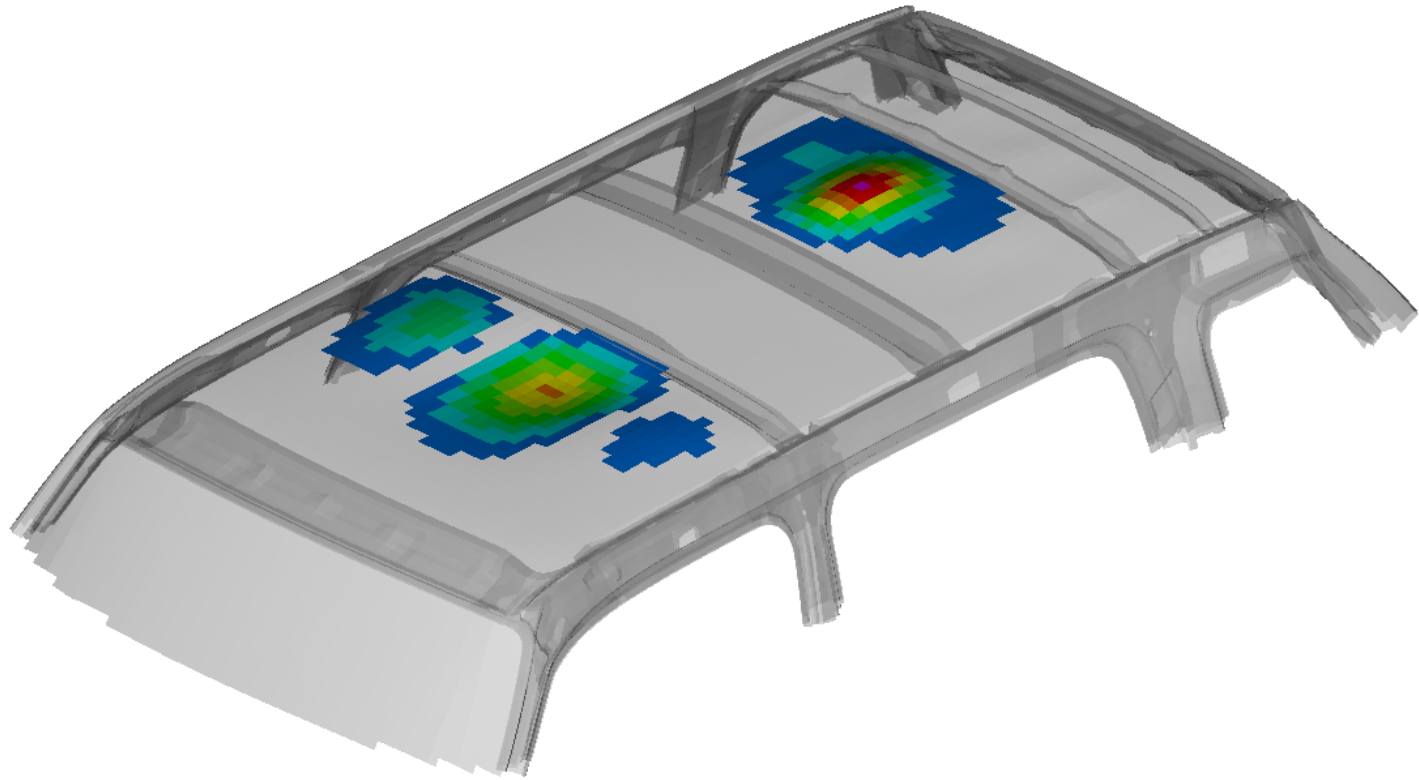
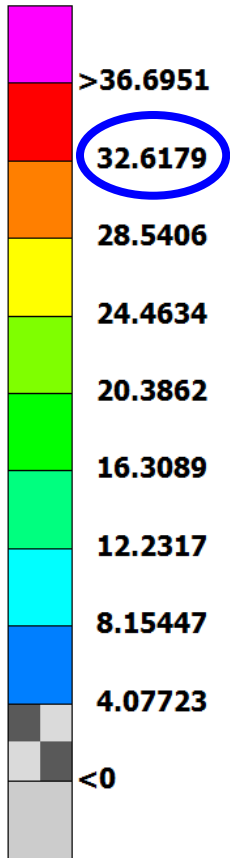
Optimal Design



Baseline : 55.8 Hz Mode



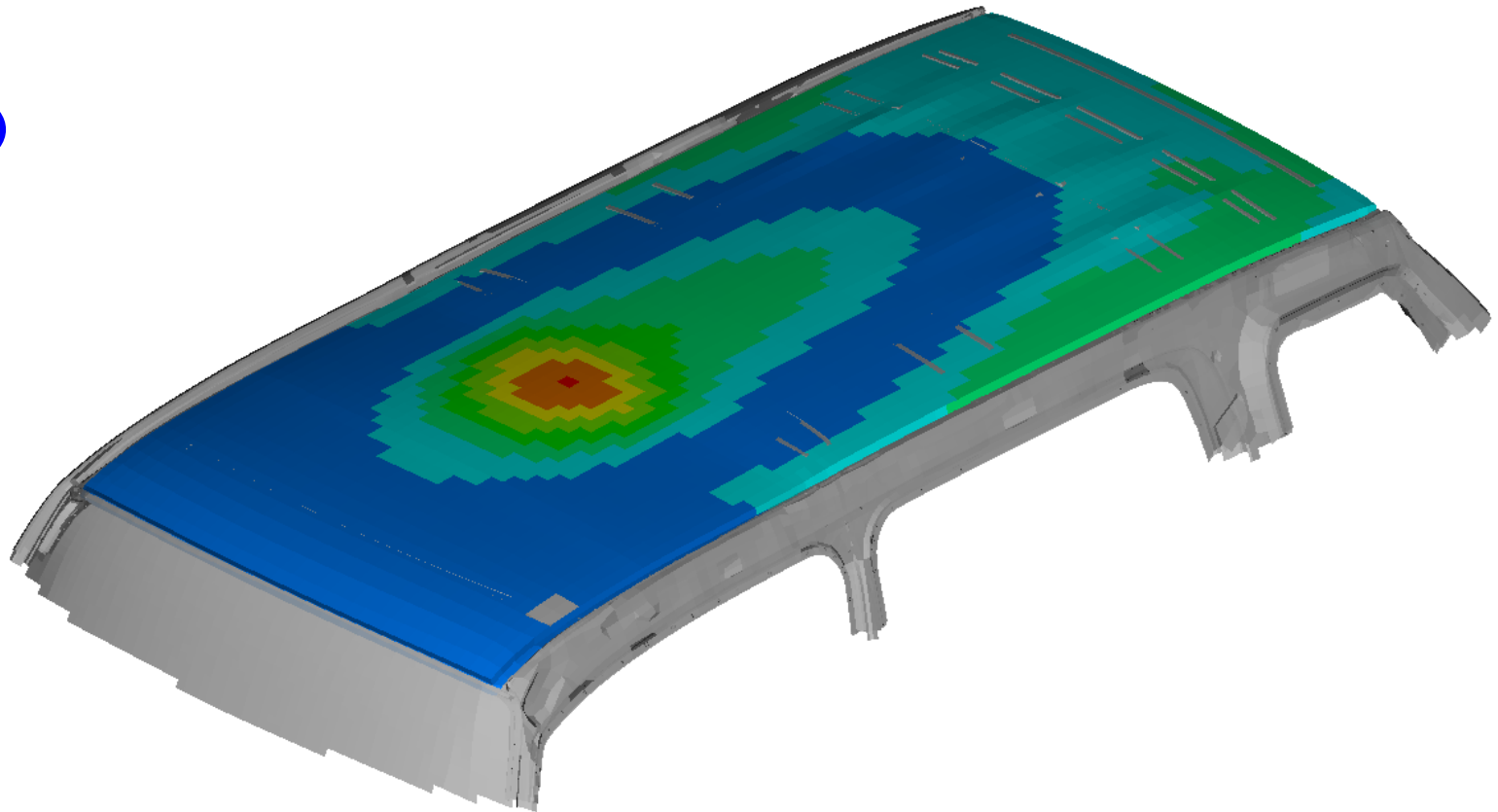
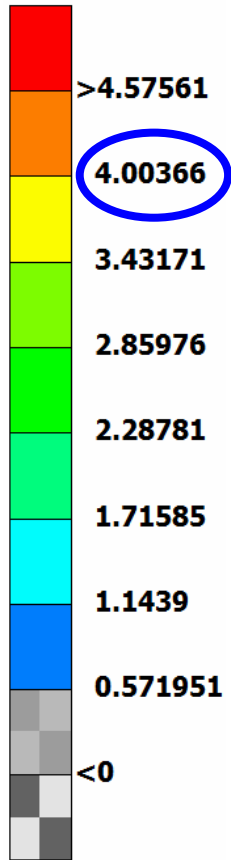
0:base_phi100.op2 : Scalar: Eigenvectors,Translational,Magnitude : : SUBCASE 1 ::MODE 23 ,FREQUENCY 5.586031E+001 ,EIGENVALUE 1.231874E+005



Optimal : 55.2 Hz Mode



0:NormalModes.op2 : Scalar: Eigenvectors,Translational,Magnitude : : Scale Factor 2.000E+000 : SUBCASE 1 ::MODE 22 ,FREQUENCY 5.520469E+001 ,EIGENVALUE 1.203128E+005

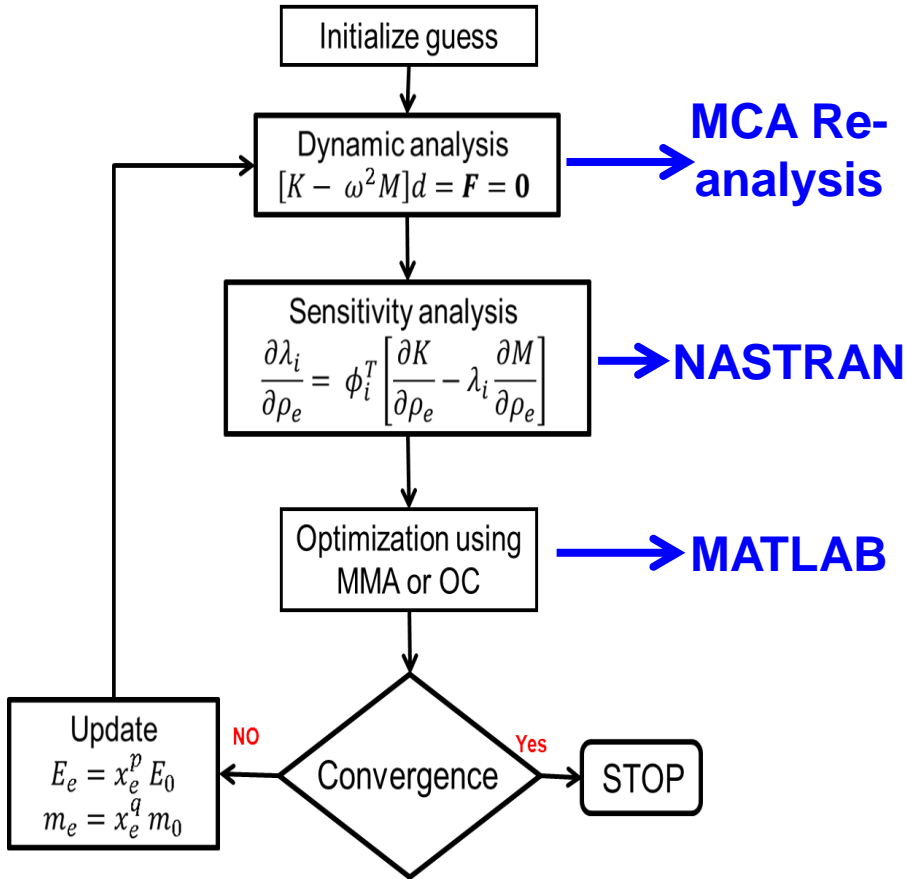




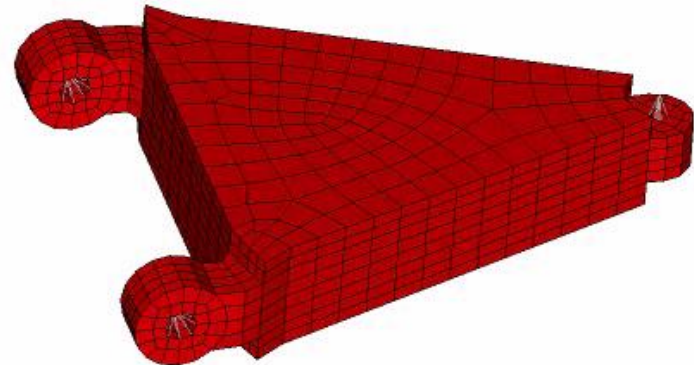
Topology Optimization with Re-Analysis Methods

- Optimizer uses MMA - Method of Moving Asymptotes (in **MATLAB**)
 - Gradient Filtering to reduce mesh dependency
 - Paulson Scheme to avoid discontinuity / checker board
- **NASTRAN** for all calculations (mass, volume, objective, constraints, AND **gradients**)
- **MCA Re-analysis** for all eigenvalue / eigenvector estimations

Topology Optimization with Re-analysis



$$\begin{aligned}
 & \max \{ \lambda_i \}, & i = 1, \dots, N_{dof} \\
 & \text{s.t. } (K - \lambda_i M)\phi_i = 0, & i = 1, \dots, N_{dof} \\
 & \sum_{e=1}^N v_e \rho_e \leq V, & 0 < \rho_{min} < \rho_e < 1, \\
 & & e = 1, \dots, N
 \end{aligned}$$

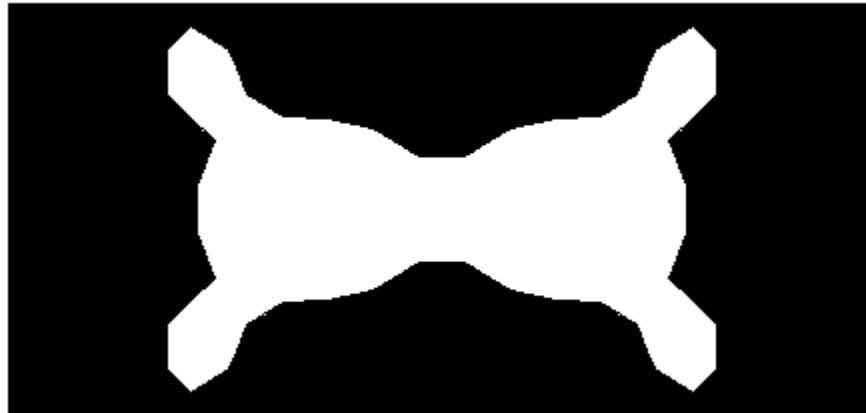


Gradient Filtering for Mesh Dependency



Fine mesh provides more detail which can result in localized small holes

**20 x 10
coarse mesh**



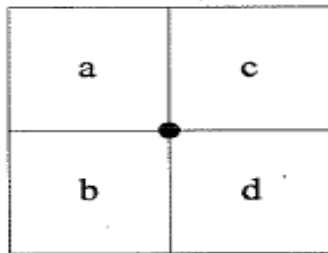
**40 x 20
fine mesh**



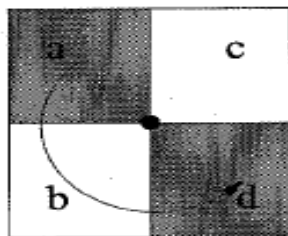
Paulson Scheme



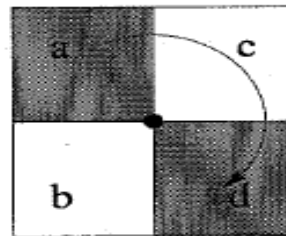
Prevents checker-board pattern producing one-node hinge connection



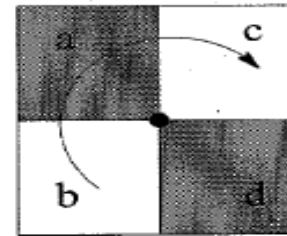
Four-element 2D example



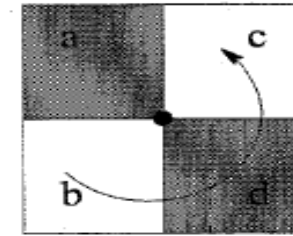
$m=2$



$m=2$

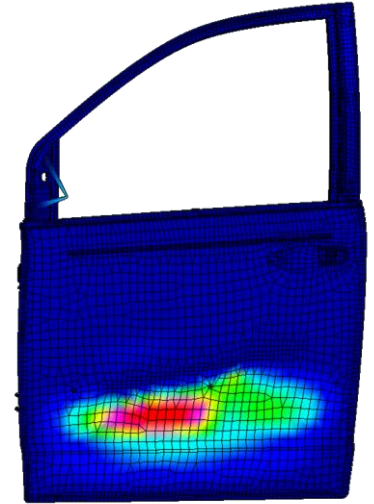
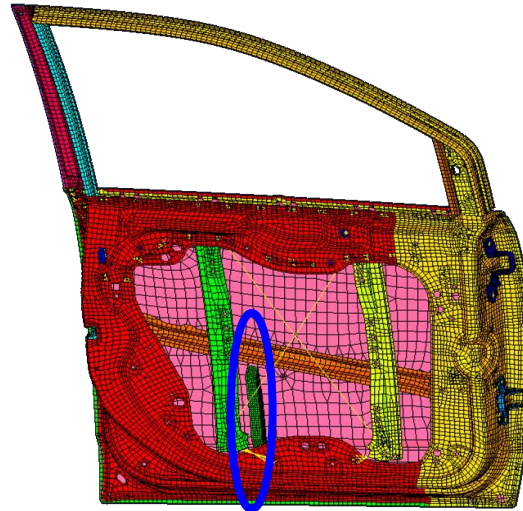
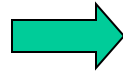
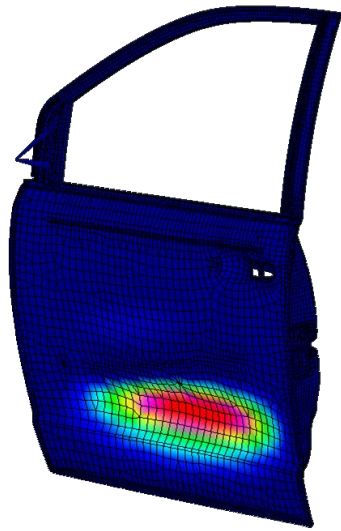


$m=2$



$m=2$

Automotive Door Example



Original Model :
32.2 Hz Mode

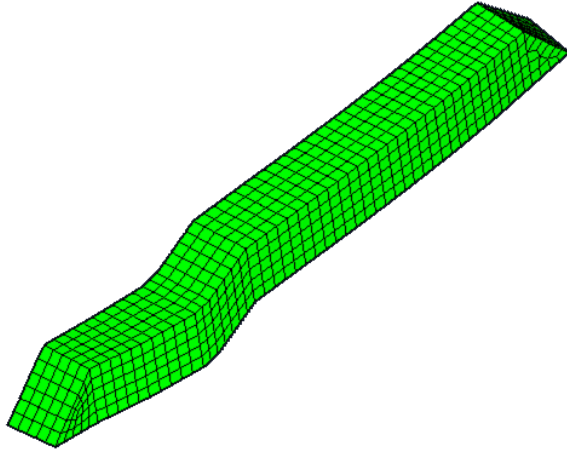
**Added
Stiffener**

Modified Model :
44.9 Hz Mode



Automotive Door Example

Stiffener Details and Optimization Problem



**848 CTRIA3 and CQUAD4 elements
(thickness of all elements are design
variables)**

Optimization Problem:

Maximize frequency such that:

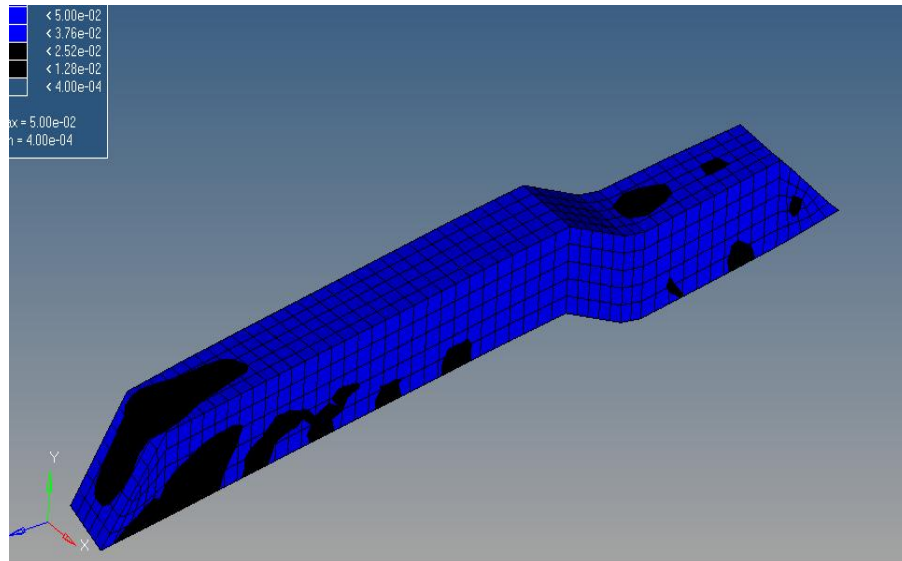
**Mass/volume of stiffener is less than
80% of original mass/volume.**

Automotive Door Example

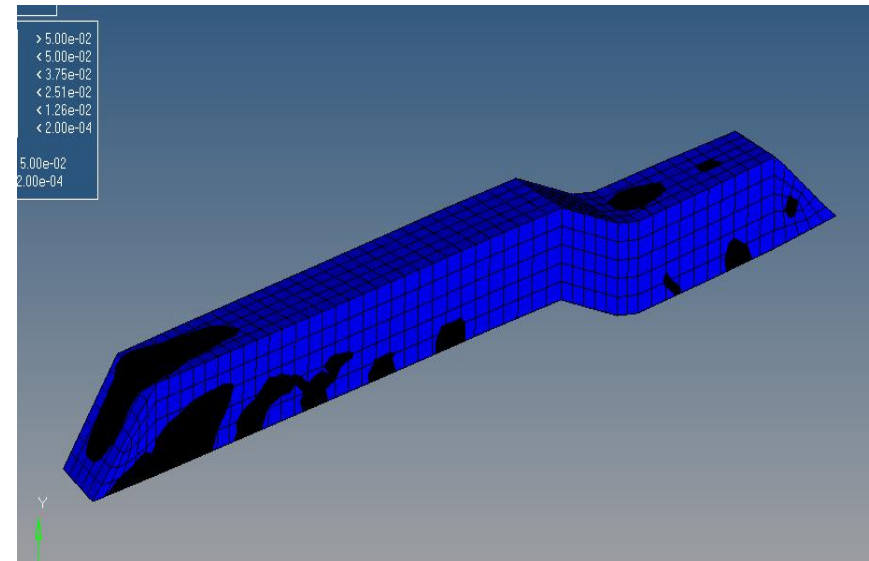
Topology Optimal Design



Gradient by Nastran



Gradient by Nastran+MCA



Using MCA reduced computational effort
from **3 hours** to **1 hour**



Summary and Conclusions

- Re-Analysis methods for **gauge**, **shape** and **topology** changes can be very effective for problems with repetitive analyses such as optimization.
 - CDH method is not recommended for shape and topology changes
 - MCA method is recommended for shape and topology changes
- Current research concentrates on refining re-analysis methods for shape, topology, and probabilistic optimization



**Thanks for your
Attention !!**

Q & A

mourelat@oakland.edu



FRF Substructuring



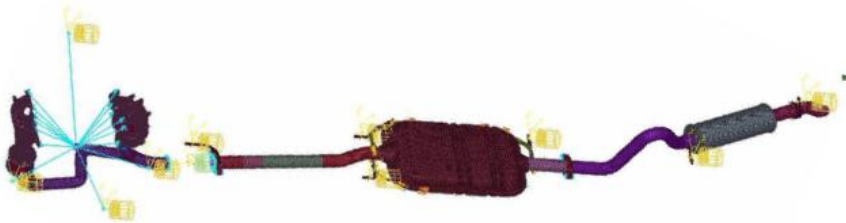
Design changes on **doors**
and/or **powertrain-exhaust**



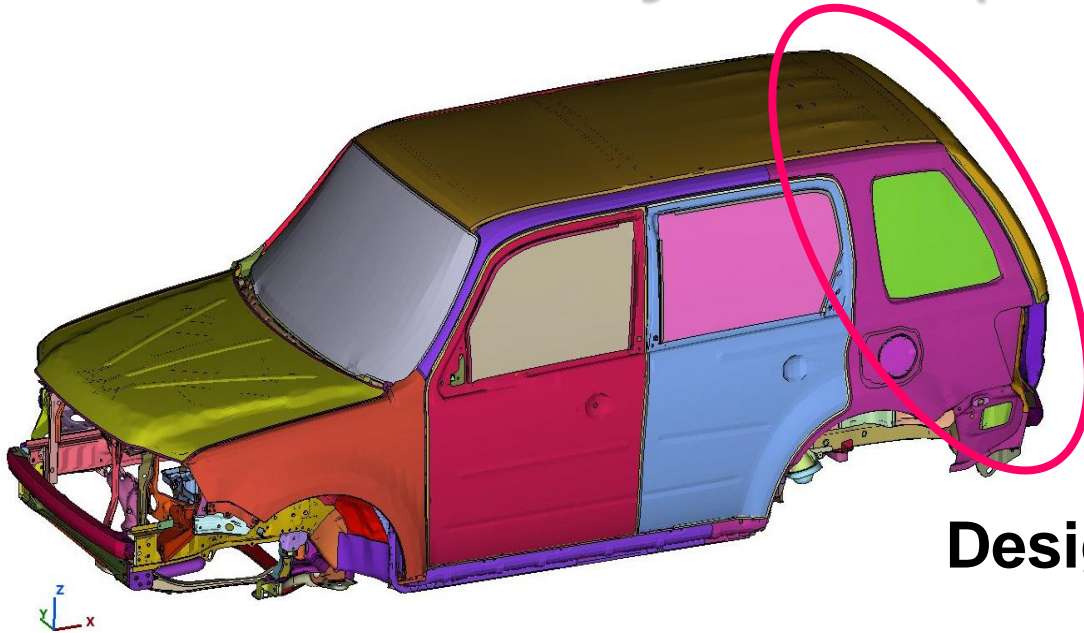
Few interface DOFs



FRF substructuring



Craig-Bampton Component Mode Synthesis (CMS)



Design changes on **rear of vehicle**



Many interface DOFs



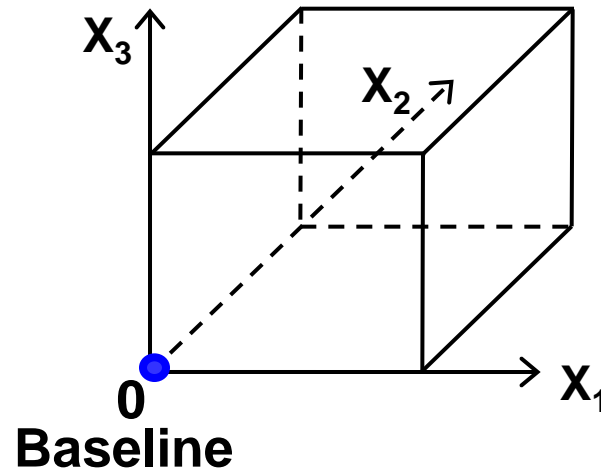
CMS (Component Mode Synthesis)

Overview / Demonstration of Re-Analysis Methods



- **CDH/VBA, MCA and PROM Re-Analysis Methods**
- **Simplified Triple Product**
 - **Polynomial Regression Method**
 - **Large Perturbation Response using Successive Iterations**
- **Re-Analysis Methods for Shape Changes**
 - **Different Examples**
 - **Shape/Gauge Optimization (Car Example)**
- **Re-Analysis in Topology Optimization**
 - **Automotive Door Example**

CDH/VBA Re-Analysis Method



$$\mathbf{K}_R = \Phi_0^T \mathbf{K} \Phi_0$$

Reduced
Matrices

$$\mathbf{M}_R = \Phi_0^T \mathbf{M} \Phi_0$$

Modal Basis at
Baseline

Modified Combined Approximation (MCA) Re-Analysis Method

Direct Solution of Modified Eigenproblem

$$\mathbf{K} \Phi = \lambda \mathbf{M} \Phi$$

or $\Phi = \lambda \mathbf{K}^{-1} \mathbf{M} \Phi$

Iterative Solution of Modified Eigenproblem

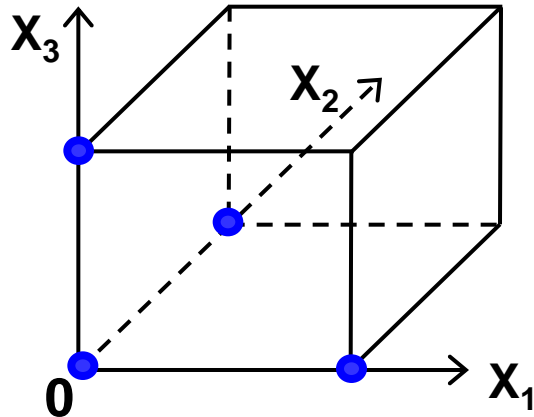
$$\Phi_j = \lambda \mathbf{K}^{-1} \mathbf{M} \Phi_{j-1}$$

Definition and formation of basis vectors

$$\mathbf{T}_1 = \mathbf{K}^{-1}(\mathbf{M} \Phi_0)$$

$$\mathbf{T}_i = \mathbf{K}^{-1}(\mathbf{M} \mathbf{T}_{i-1}) \quad i = 2, 3, \dots, s$$

$$\mathbf{T} = [\Phi_0 \quad \mathbf{T}_1 \quad \mathbf{T}_2 \quad \dots \quad \mathbf{T}_s]$$



Baseline

X_1, X_2, X_3 : design variables

Eigen-analysis of full matrices

$$eig(\mathbf{K}, \mathbf{M}) \Rightarrow \lambda, \Phi$$

- **Advantage**: Re-analysis is done using the reduced basis
- **Disadvantage**: Condensation of matrices can be expensive due to large size and high density of mode matrix \mathbf{P}

1. Form reduced basis:

$$\mathbf{P} = [\Phi_0 \quad \Phi_1 \quad \Phi_2 \quad \Phi_3]$$

2. Project system matrices to reduced basis:

$$\mathbf{K}_R = \mathbf{P}^T \mathbf{K} \mathbf{P} \quad \mathbf{M}_R = \mathbf{P}^T \mathbf{M} \mathbf{P}$$

3. Eigen-analysis of reduced matrices:

$$eig(\mathbf{K}_R, \mathbf{M}_R) \Rightarrow \tilde{\lambda}^p, \Theta$$

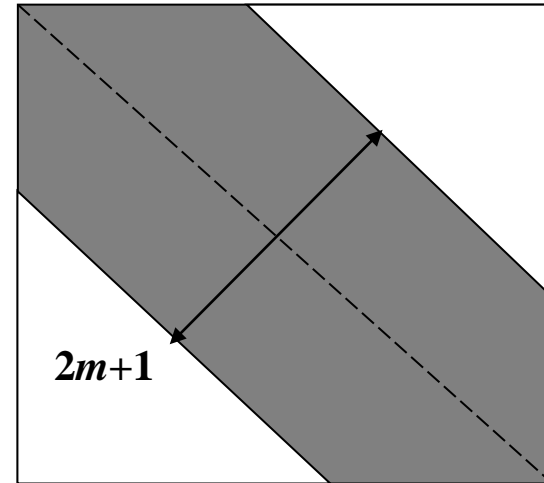
4. Obtain approximate eigenvectors:

$$\tilde{\Phi} = \mathbf{P} \Theta$$

Simplified Triple Product



100% density for condensed K and M



Density is :

$$\frac{(2m+1)n - (m+1)m}{n^2} \approx \frac{2m+1}{n}$$

$n \gg m$

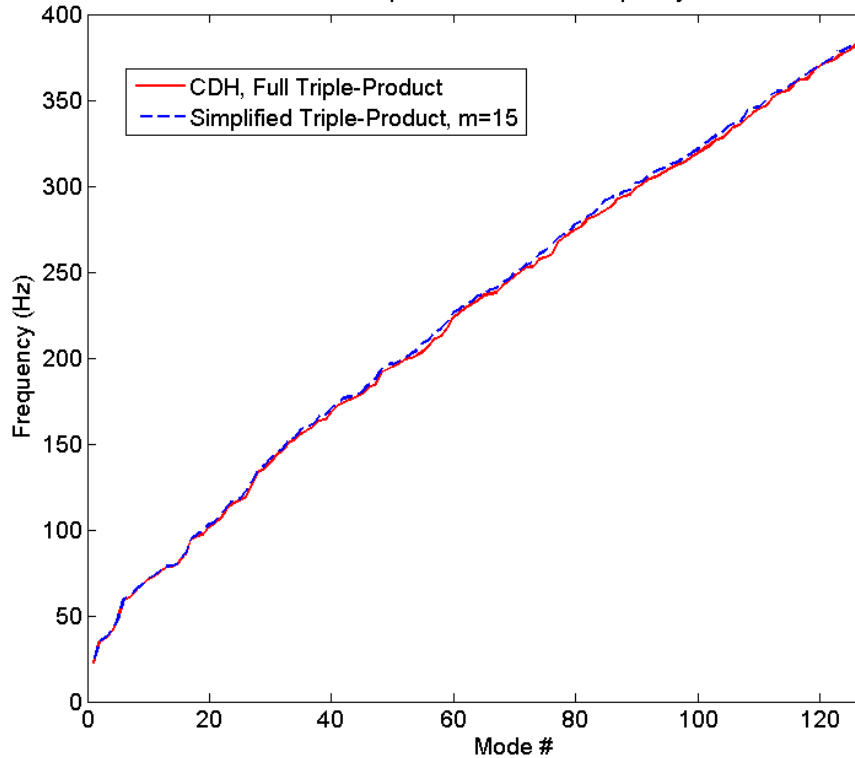
n : **Number of DOFs**

Computational cost is approximately equal to $(2m+1)/n$ of full triple-product cost

Simplified Triple Product



Comparison of Natural Frequency

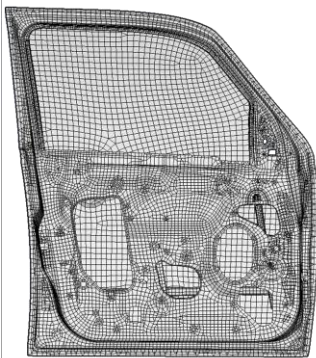
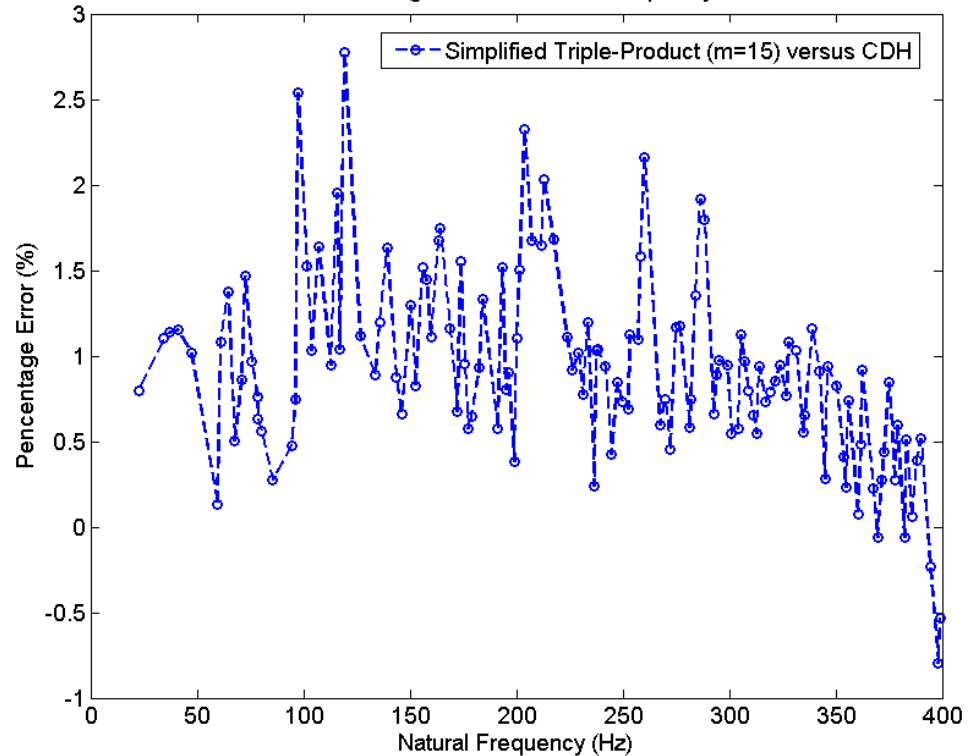


$m = 15$

Density : 13.1 %

20% increase of outer shell thickness

Percentage Error of Natural Frequency





Example: Thin shell elements without transverse shear

$$\mathbf{K} = \mathbf{A}_0 + \mathbf{A}_1 t + \mathbf{A}_2 t^3 \quad \mathbf{A}_i, \quad i = 0,1,2 \quad \text{are fixed matrices}$$

Shell thickness

Similarly :

$$\mathbf{K}^r = \mathbf{A}_0^r + \mathbf{A}_1^r t + \mathbf{A}_2^r t^3 \quad \text{with} \quad \mathbf{A}_i^r = \mathbf{\Phi}^T \mathbf{A}_i \mathbf{\Phi}$$

Polynomial Regression for Triple Product



Calculate triple products for **3 different thicknesses** :

$$\begin{bmatrix} 1.0 & t_0 & t_0^3 \\ 1.0 & t_1 & t_1^3 \\ 1.0 & t_2 & t_2^3 \end{bmatrix} \begin{bmatrix} \mathbf{A}_0^r \\ \mathbf{A}_1^r \\ \mathbf{A}_2^r \end{bmatrix} = \begin{bmatrix} \mathbf{K}_0^r \\ \mathbf{K}_1^r \\ \mathbf{K}_2^r \end{bmatrix} \Rightarrow \mathbf{A}_i^r, \quad i = 0,1,2$$

Then:

$$\mathbf{K}^r = \mathbf{A}_0^r + \mathbf{A}_1^r t + \mathbf{A}_2^r t^3$$

Similar expressions exist for K and M matrices of plate and solid elements.

Large Perturbation Response using Successive Iterations



1. Calculate the **baseline** eigenvectors Φ_0 .
2. **Perturb design variables by 5%** or so. Use **Polynomial Regression approach** to calculate reduced matrices

$$\mathbf{K}_r^1 = \Phi_0^T \mathbf{K}_1 \Phi_0 \quad \text{and} \quad \mathbf{M}_r^1 = \Phi_0^T \mathbf{M}_1 \Phi_0$$

Small Size

and solve eigenvalue problem $\mathbf{K}_r^1 \Phi_r^1 = \mathbf{M}_r^1 \Phi_r^1 \Lambda_r$ for eigenvectors Φ_r^1 . The eigenvectors of the perturbed structure are equal to $\Phi_1 = \Phi_0 \Phi_r^1$.

3. Repeat step 2 until the maximum value of all design variables is reached. The following **recursive process** is used for $i = 1, 2, \dots, n$:

$$\mathbf{K}_r^i = \Phi_{i-1}^T \mathbf{K}_i \Phi_{i-1} \quad \text{and} \quad \mathbf{M}_r^i = \Phi_{i-1}^T \mathbf{M}_i \Phi_{i-1}$$

$$\mathbf{K}_r^i \Phi_r^i = \mathbf{M}_r^i \Phi_r^i \Lambda_r$$

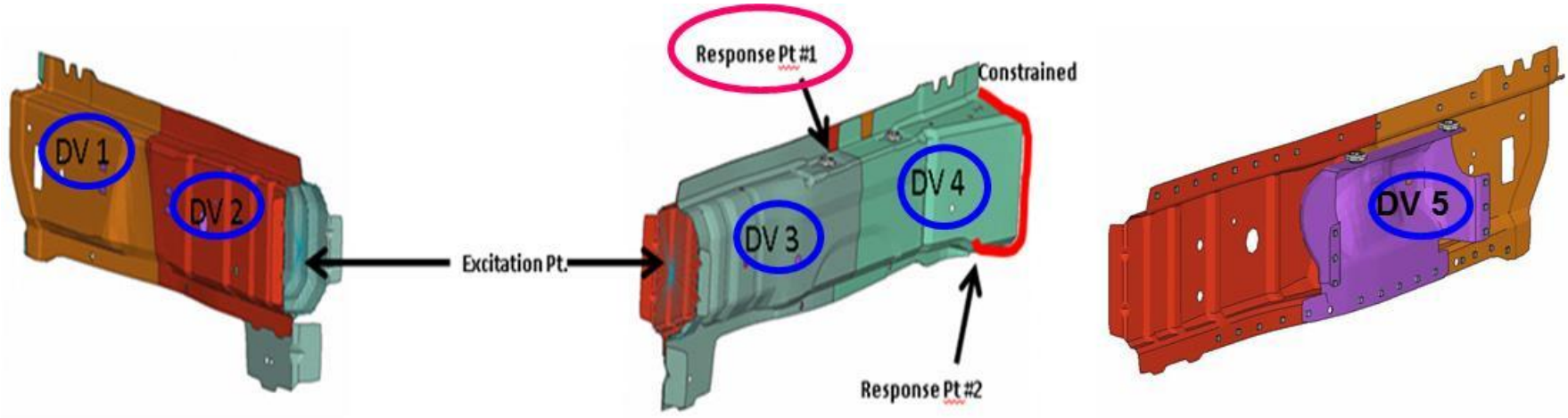
$$\Phi_i = \Phi_{i-1} \Phi_r^i$$

Polynomial Regression

- **No K and M matrix updates needed**
- **No triple product calculation is needed**
- **Only small eigenvalue problems are solved**

Method assumes Polynomial Regression is applicable

Automotive Rail Example

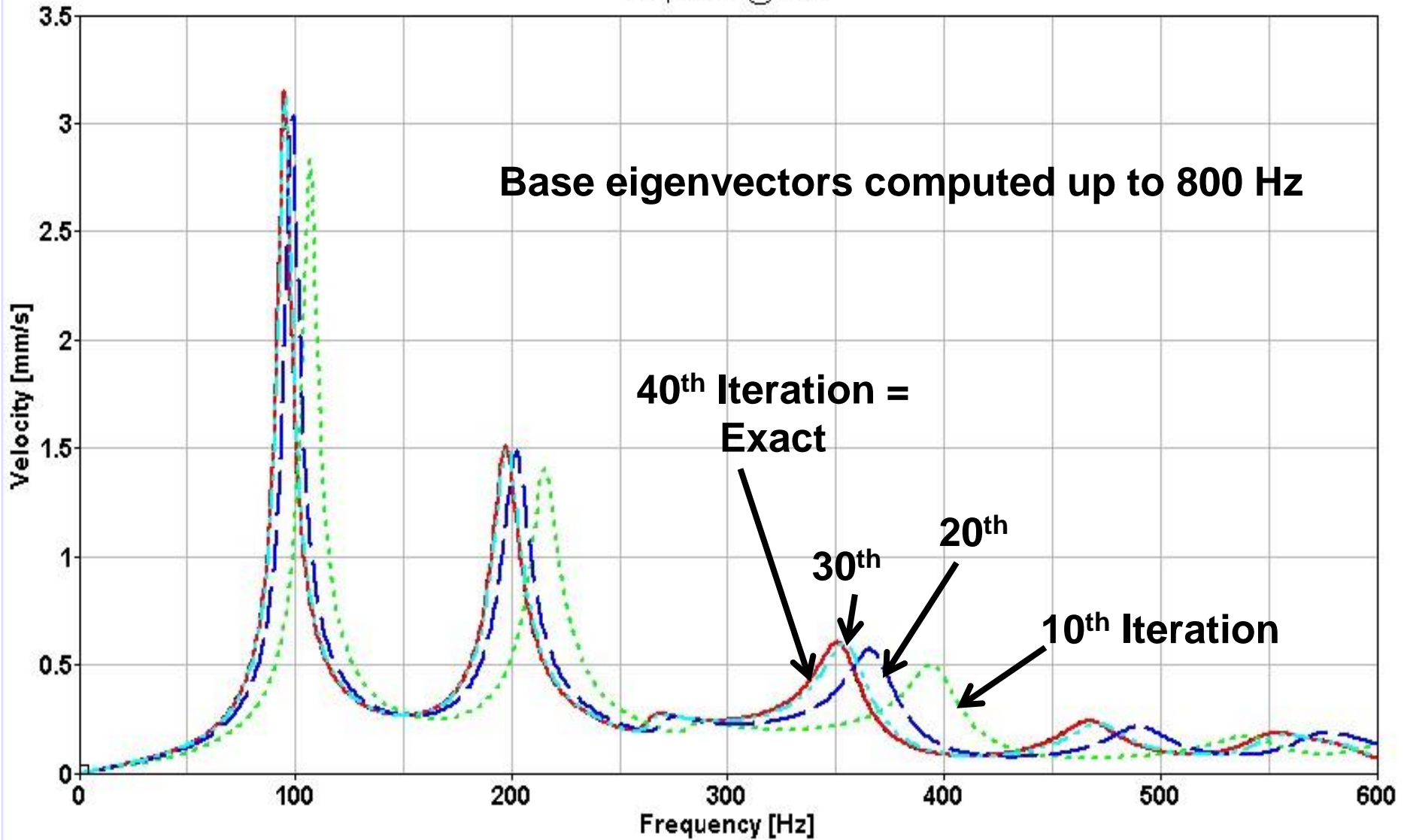


Design Variable	Min Thickness (mm)	Max Thickness (mm)	Perturbation %
1	1.025	3.075	200
2	1.16	3.48	200
3	1.25	3.75	200
4	1.16	3.48	200
5	1.25	3.75	200

Automotive Rail Example



Response @ Pt. 1



Basis Creation / Ortho-normalization



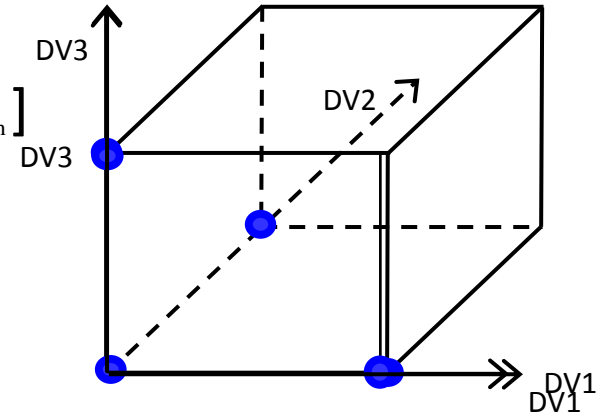
Reduction in BASIS size

Eliminate design variables

$$\Phi = [\Phi_1 \quad \cancel{\Phi_2} \quad \cancel{\Phi_3} \quad \Phi_4 \quad \dots \quad \Phi_n]$$



$$\Phi = [\Phi_1 \quad \Phi_4 \quad \dots \quad \Phi_n]$$



Eliminate some modes

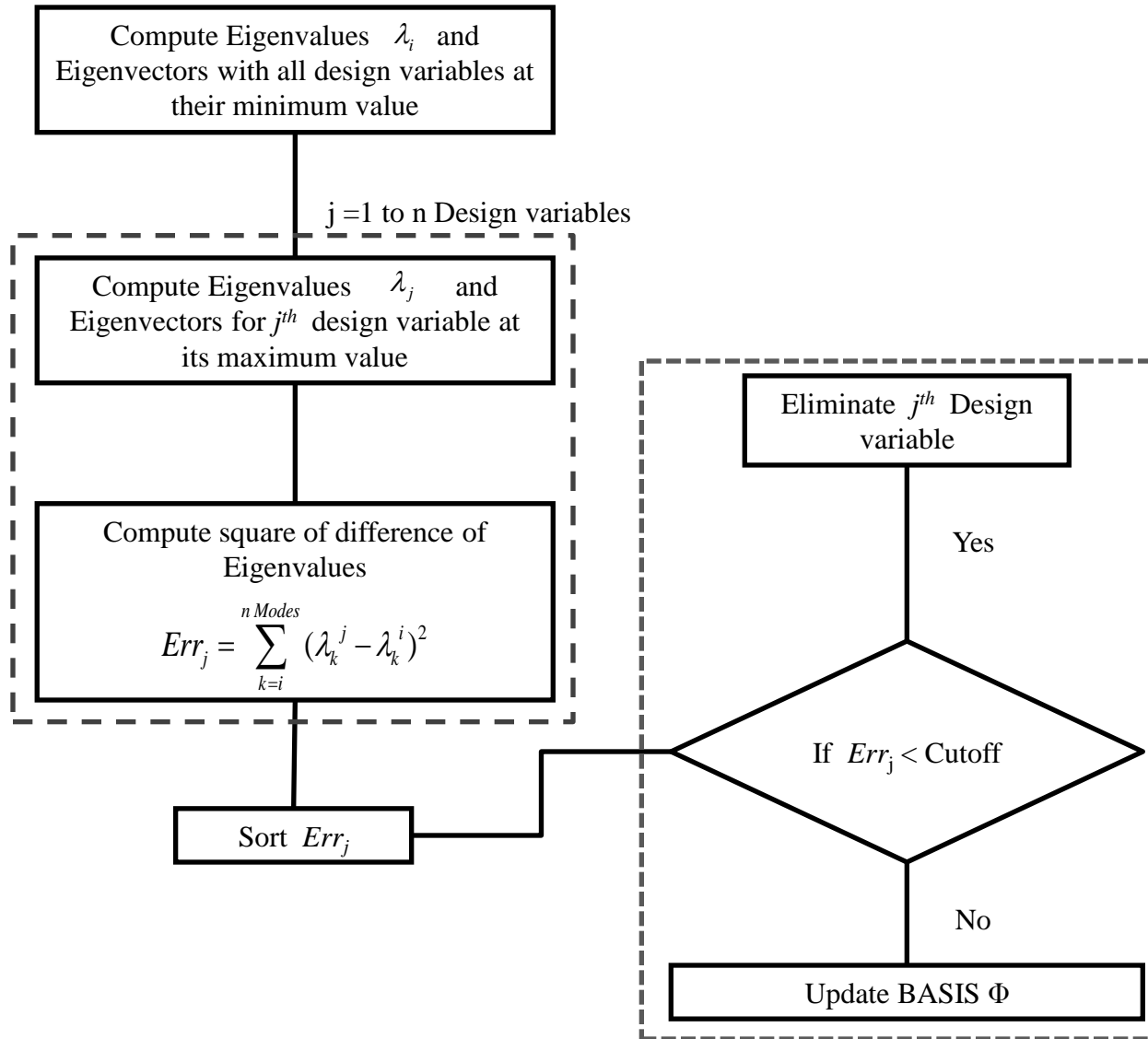
$$\Phi_i = \begin{bmatrix} \lambda_{11} & \cancel{\lambda_{12}} & \lambda_{13} & \cancel{\lambda_{14}} & \lambda_{15} & \cancel{\lambda_{16}} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \lambda_{41} & \cancel{\lambda_{42}} & \lambda_{43} & \cancel{\lambda_{44}} & \lambda_{45} & \cancel{\lambda_{46}} \end{bmatrix}$$



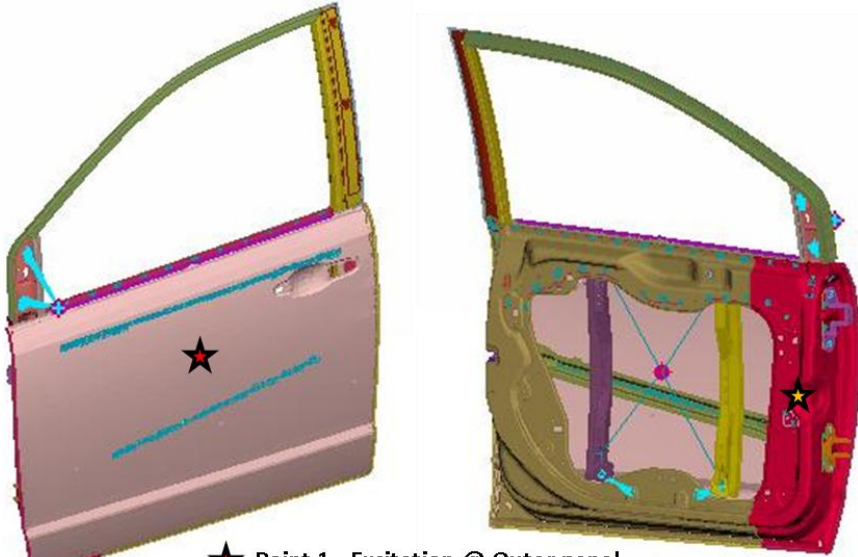
$$\Phi_i = \begin{bmatrix} \lambda_{11} & \lambda_{13} & \lambda_{15} \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \\ \lambda_{41} & \lambda_{43} & \lambda_{45} \end{bmatrix}$$

Less time to Ortho-normalize

Elimination of Design Variables



Elimination of Design Variables



★ Point 1 - Excitation @ Outer panel
 ★ Point 2 - Excitation @ Inner panel

**Automotive door
 example with
 1,46,589 DOF**

#	Design Variable Description	Minimum	Maximum
Thickness (mm)			
1	Inner Door panel RHS	1	3
2	Door impact bar	1	2.75
3	Inner Door panel LHS	0.5	1.75
4	Upper door hinge reinforcement	1	3
5	Door surround rear	0.25	1.25
6	Outer panel	0.25	1.25
7	Door latch reinforcement	1	2
8	Door surround rear	1.25	3.25
9	Door belt inner	0.75	1.75
10	Glass channel mounting brkt.	1.25	2.25
11	Door surround rear	0.25	1.25
12	Inner/Outer panel skirt	1	3
13	Inner/Outer panel skirt	2	4
14	Door belt outer	0.25	1.25
15	Door surround glass	0.25	1.25
16	Impact bar bracket	1	3
17	Door Inner belt skirt	1	3
18	Glass runner	0.25	1
Mass (Tonne)			
19	Side view mirror mass	0.001	0.002
20	Door trim mass	0.00035	0.0005

Elimination of Design Variables



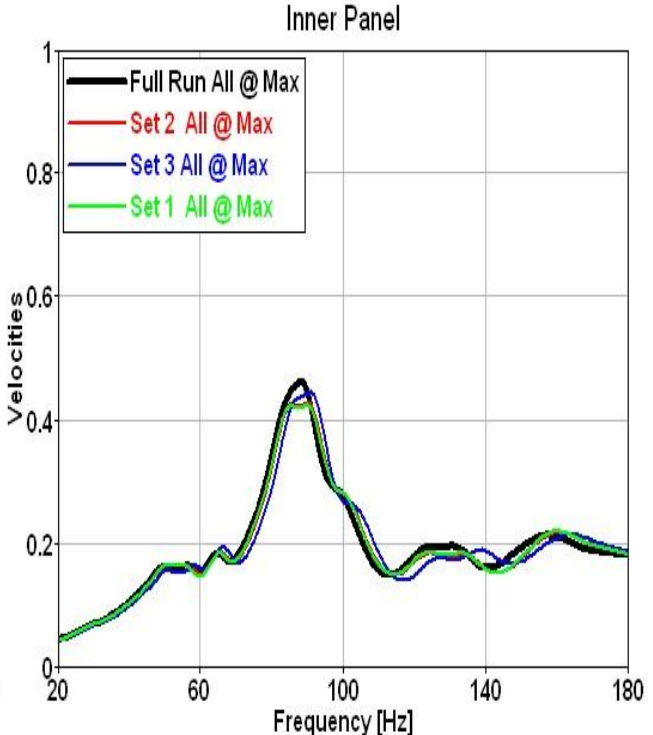
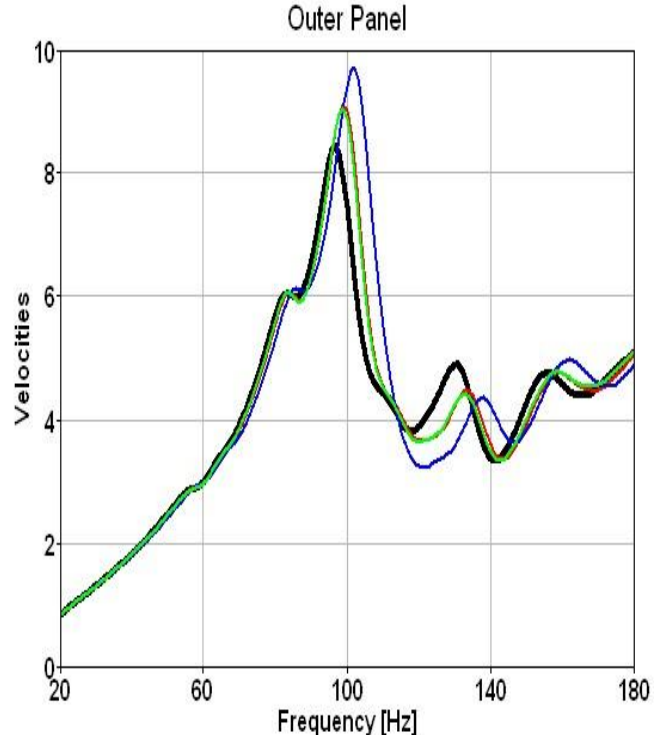
3568 for all

220 for all

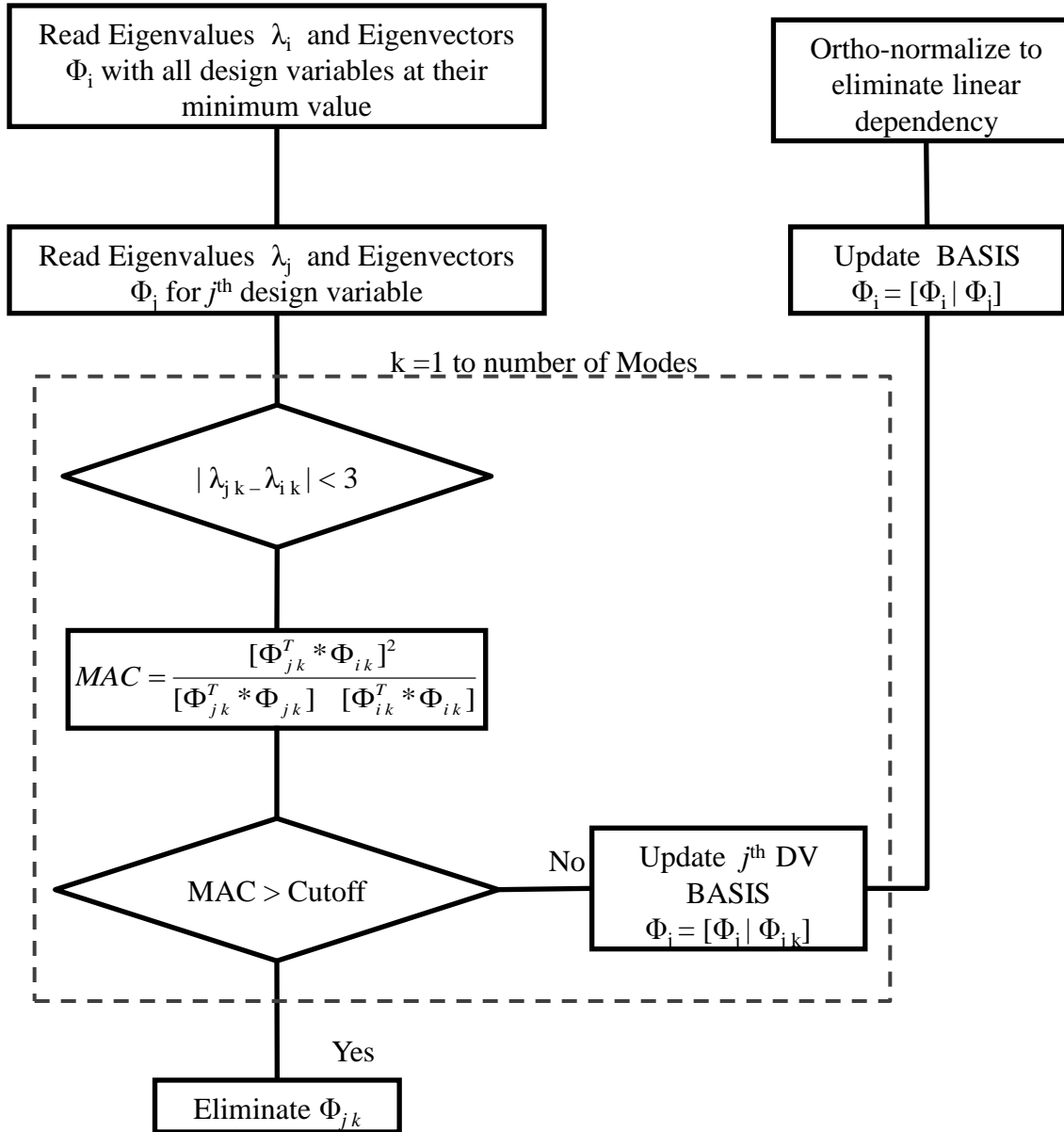
DV	Sorted Sum of Error Squared
6	370152.80
3	18147.88
14	3003.77
1	2965.82
9	867.31
15	330.78
10	151
11	121.24
5	115.34
19	115.21
18	111.67
17	105.51
2	78.83
16	73.11
7	49.56
8	49.47
12	44.23
13	10.97
20	5.53
4	0.56



BASIS Set #	Eliminated Design Variable	Vector columns in BASIS	Time (min) for Ortho-Normalization
1	4, 20, 13	3040	85
2	4, 20, 13, 12, 8,7	2513	72
3	4, 20, 13, 12, 8,7,16,2,18,17	1810	50



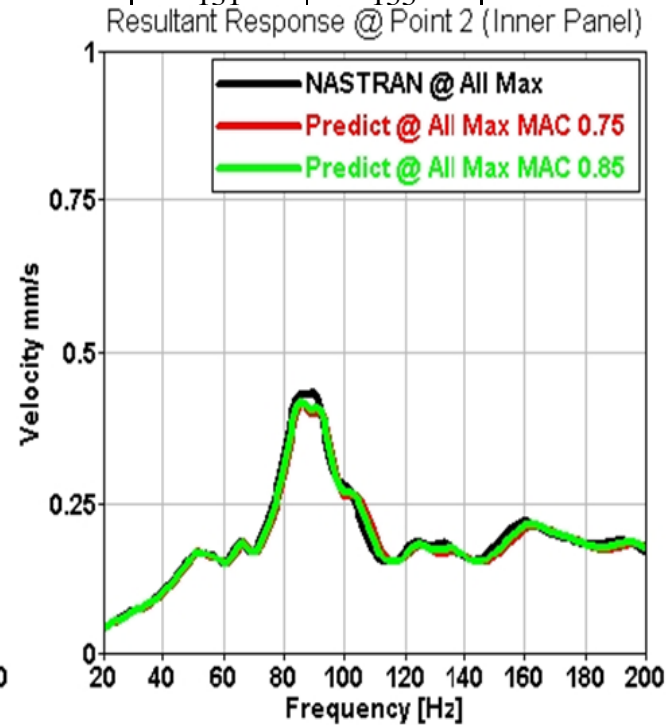
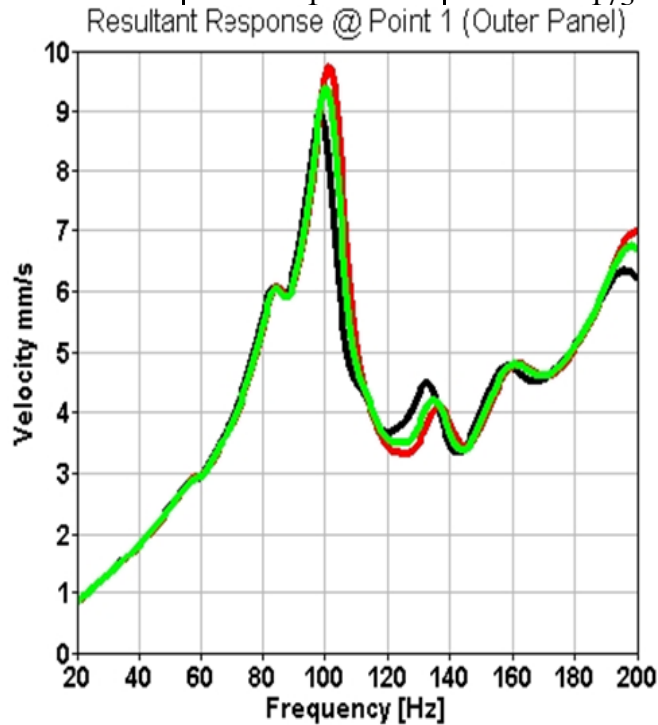
Mode Elimination



Mode Elimination



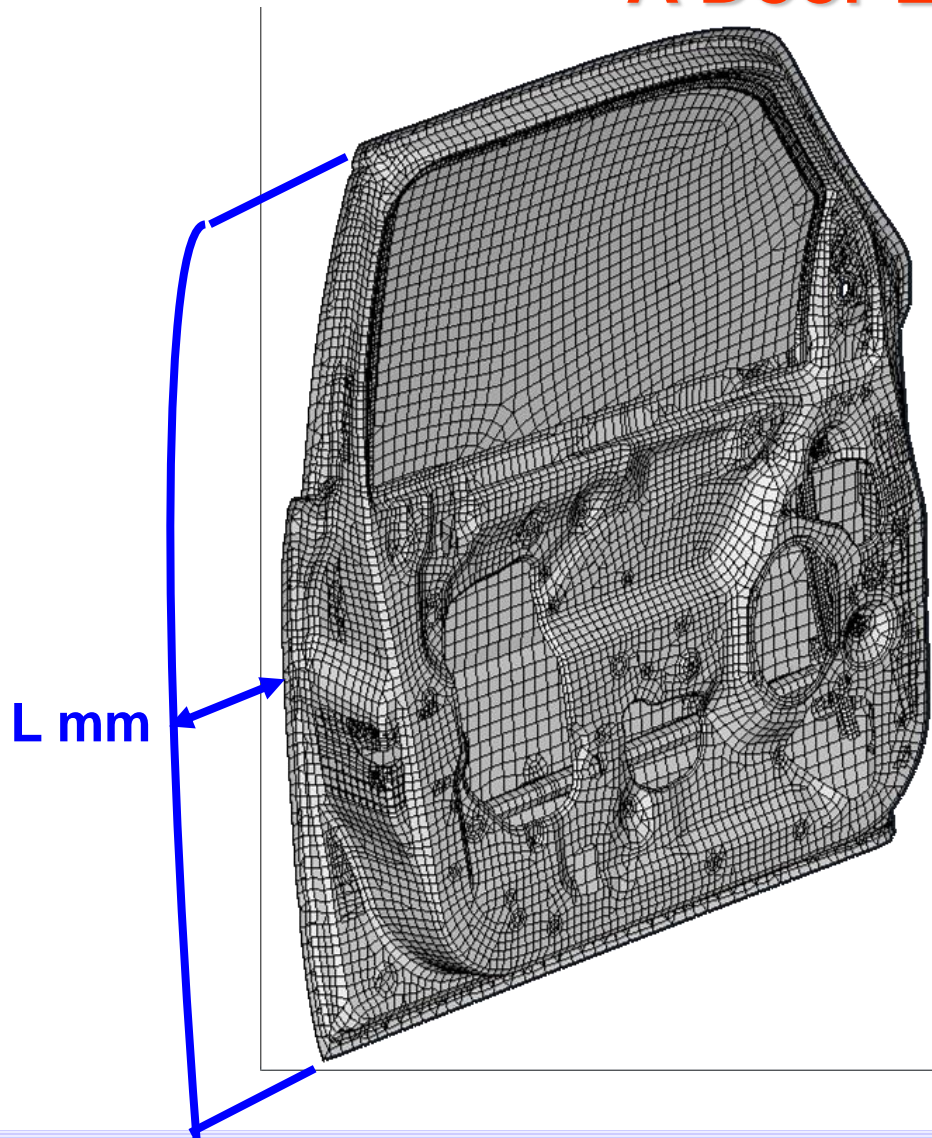
DV	No. of BASIS columns when corresponding DV is at max value only	Size Reduction	
		MAC 0.75	MAC 0.85
BASE Model	176	176	176
1	173	131	155



Total BASIS columns	3568	1138	1478
% Reduction		68.11	58.58
Time (min.) in Ortho-Normalization and Mode elimination	220	90	75

PROM and MCA for Shape Changes

A Door Example

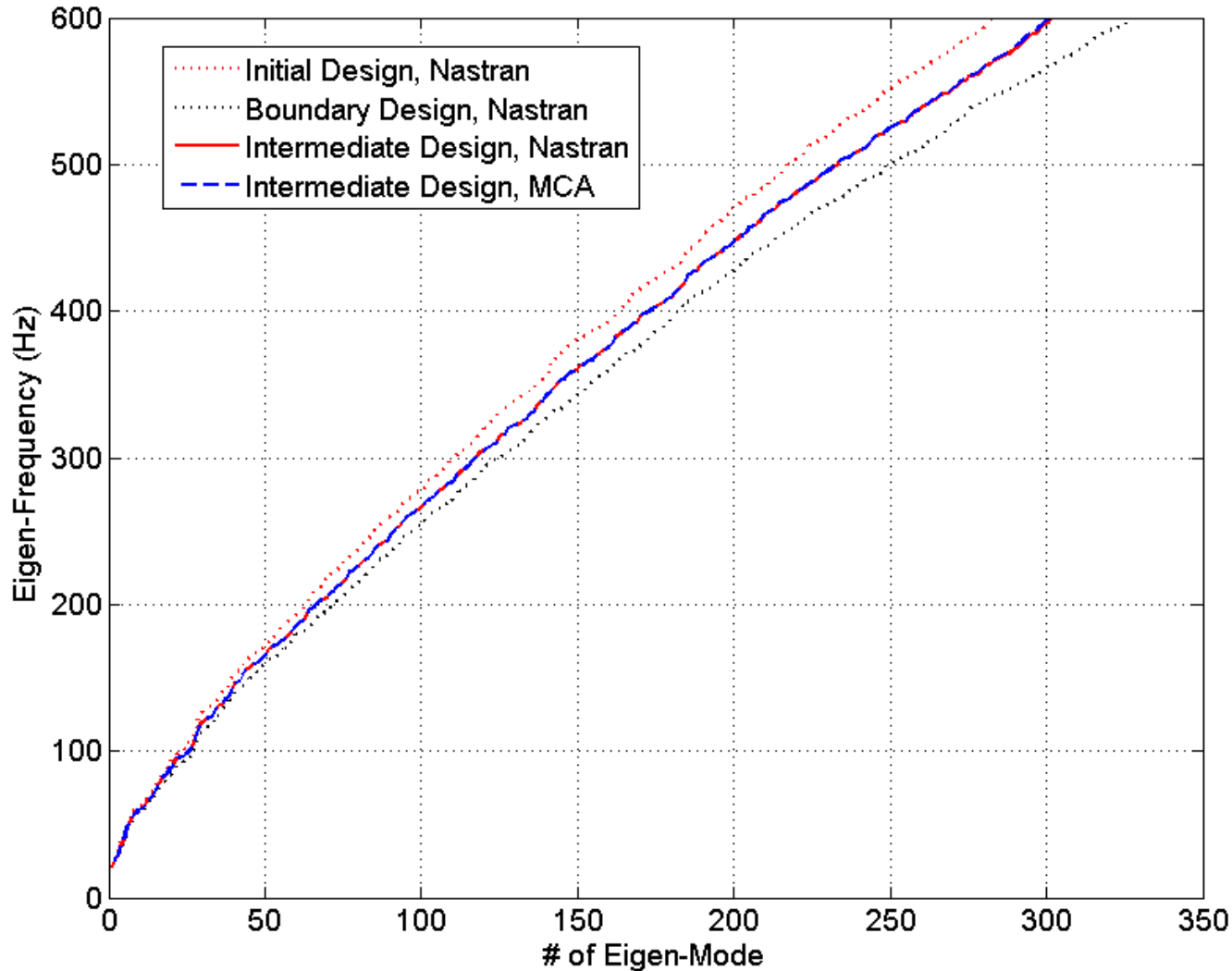


Same number of DOFs

- 150K DOFs
- Maximum $L = 152$ mm
- New Design $L = 76$ mm

PROM and MCA for Shape Changes

A Door Example

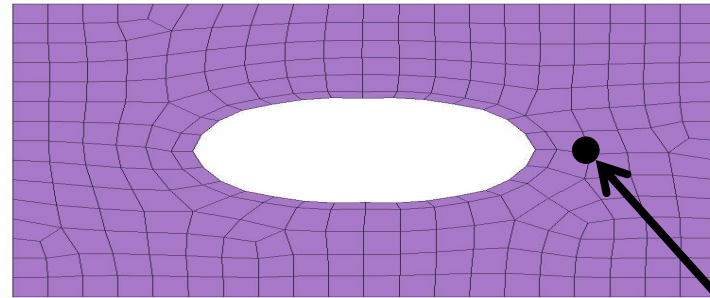
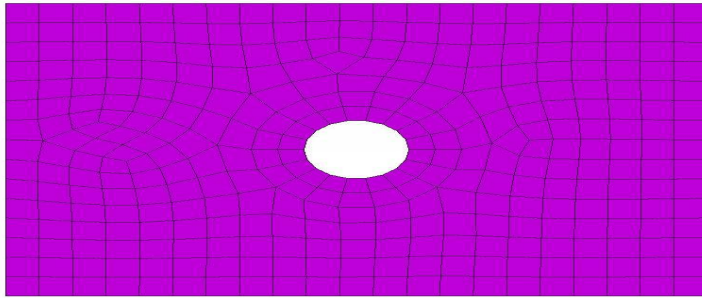


MCA Re-Analysis

Error less than 0.01%

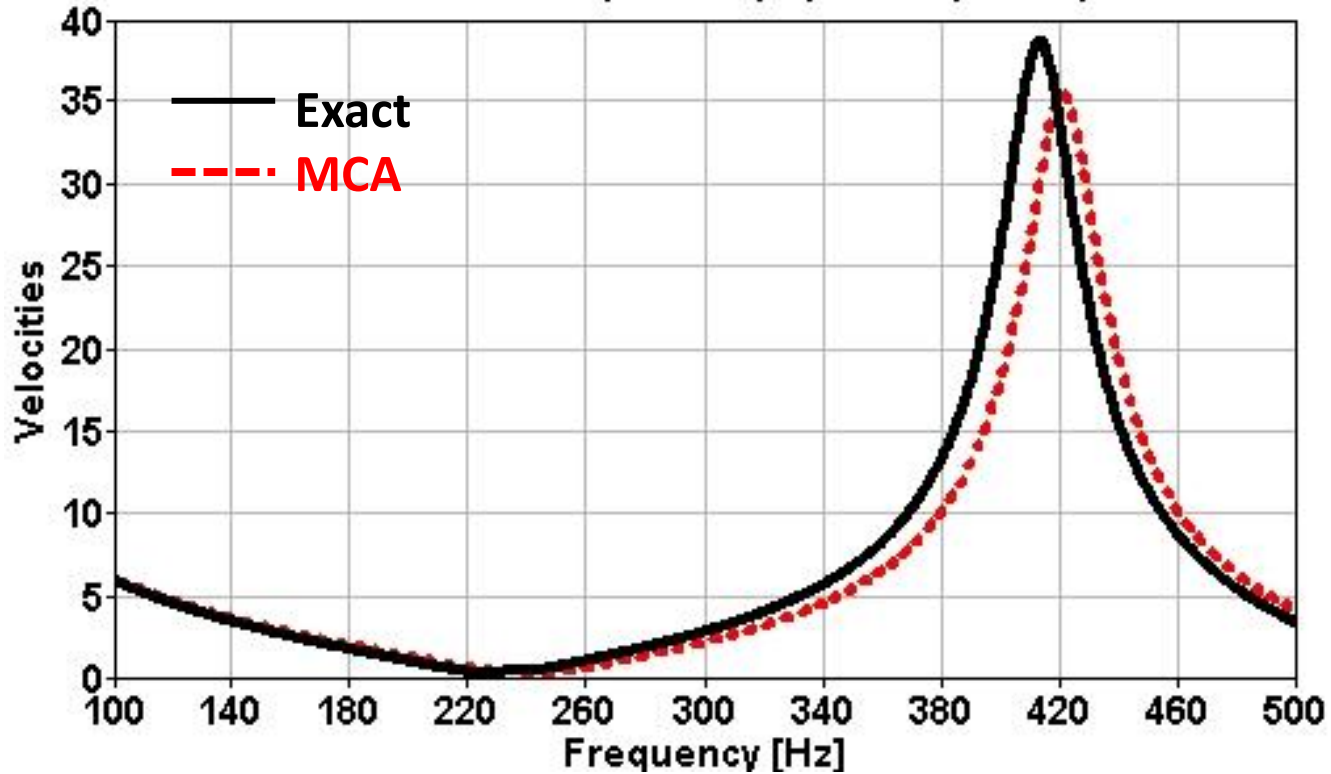
**MCA cost
= 1/2 of
PROM**

MCA for Shape Changes: Different DOFs



Point id 2507 (Out of paper response)

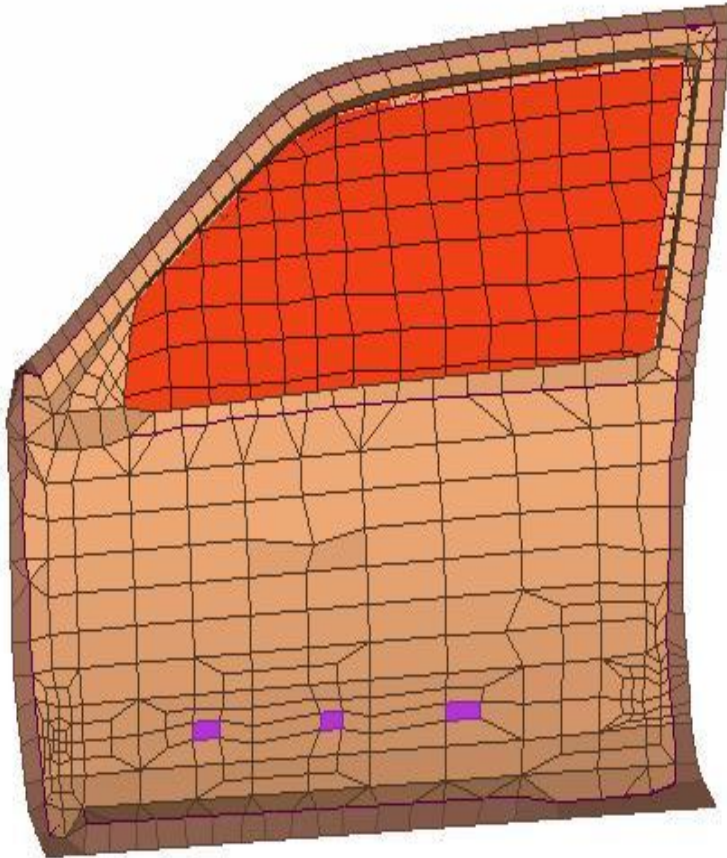
2507



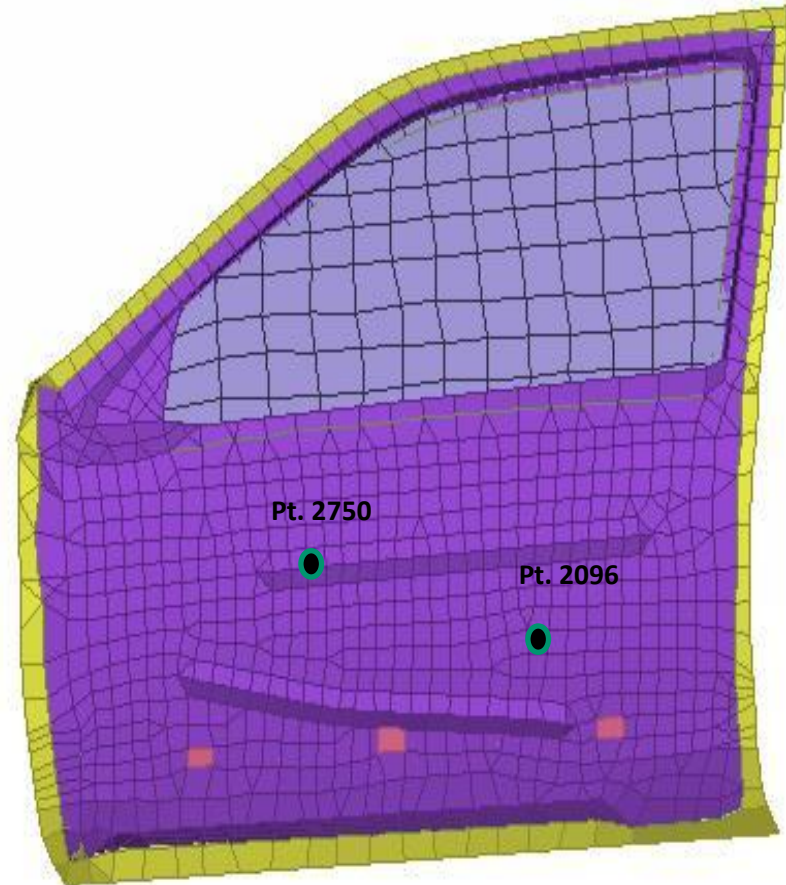
MCA for Shape Changes: **Different DOFs**



Original Model



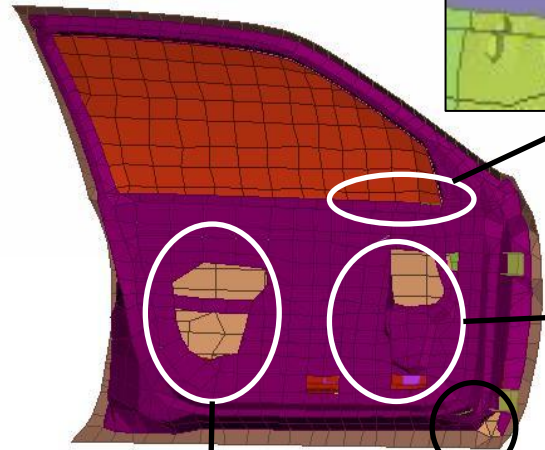
New Model



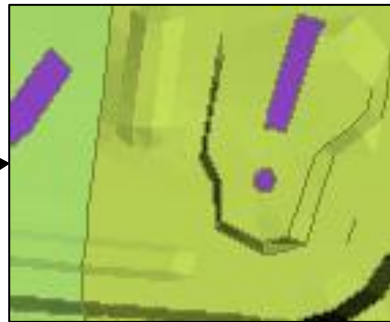
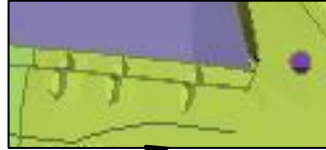
MCA for Shape Changes: **Different DOFs**



Original Model



Added Beads and Hole



Revised Pattern and Added Beads

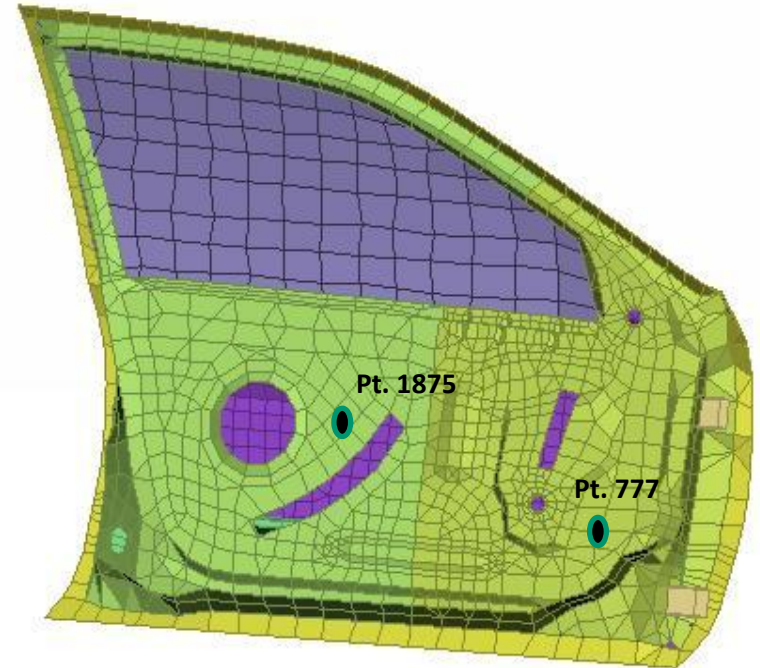


Hole Pattern revised



Section moved in

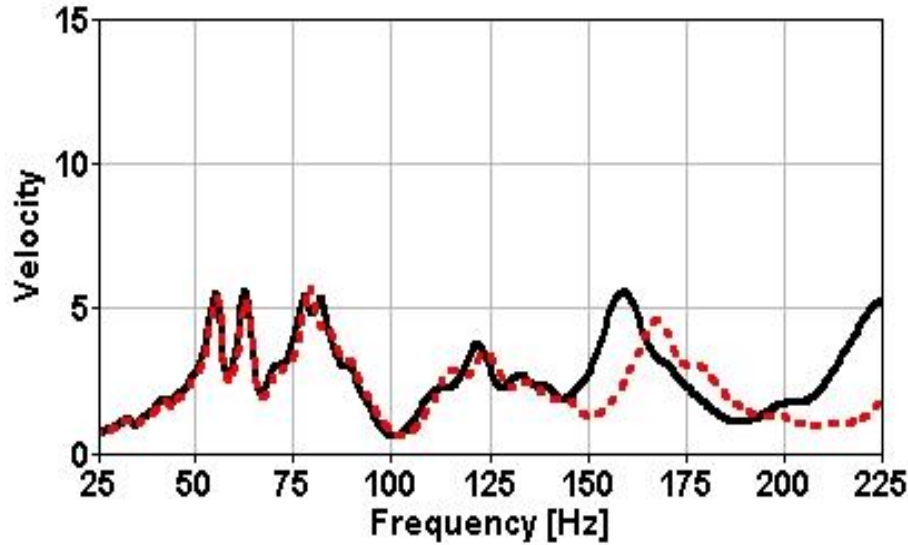
New Model



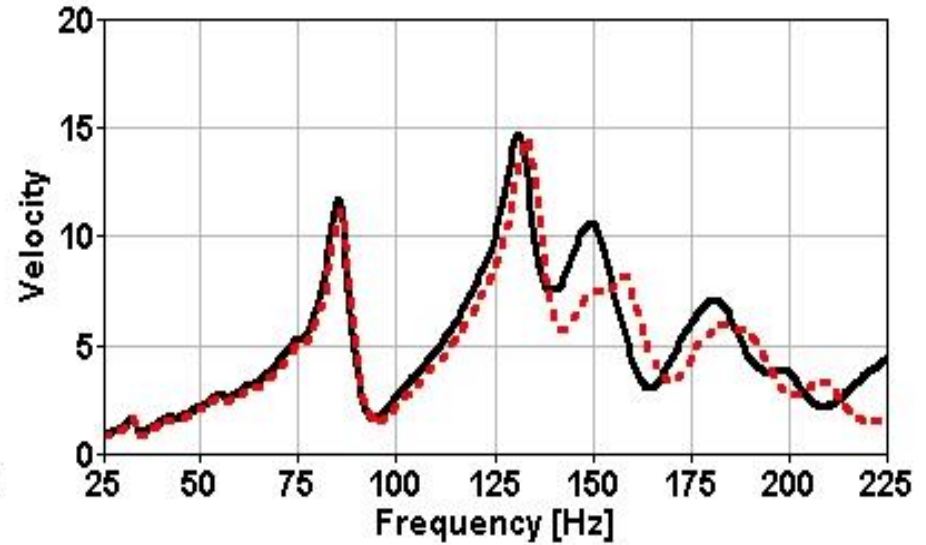
MCA for Shape Changes: Different DOFs



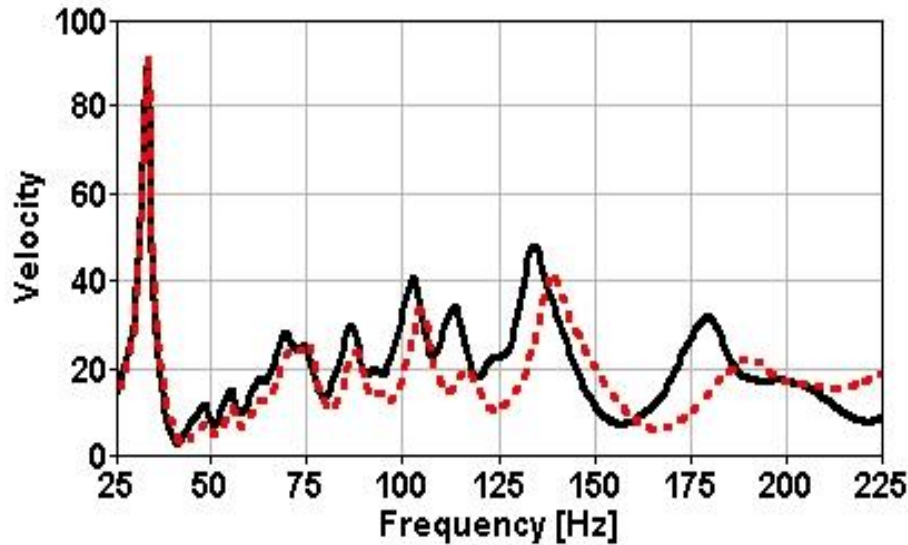
OUTERPANEL Point 2750



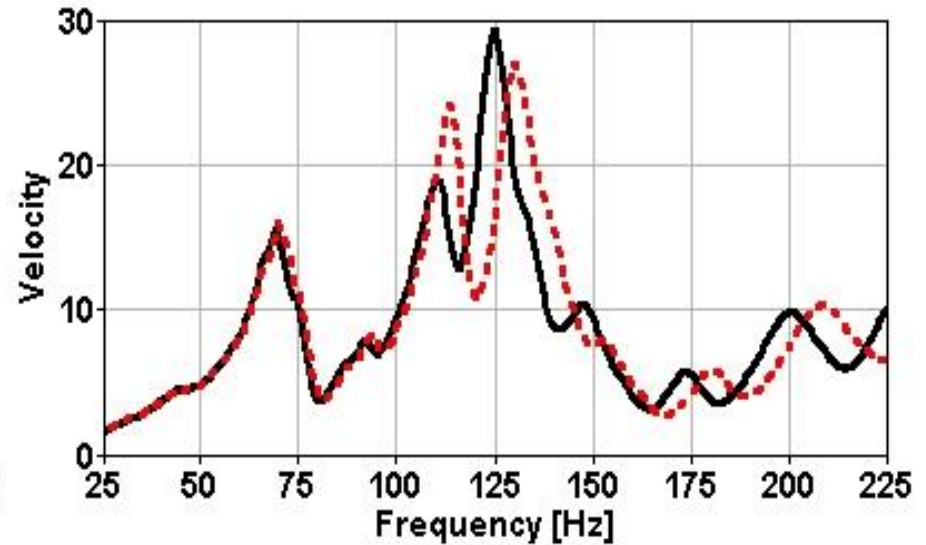
OUTERPANEL Point 2096



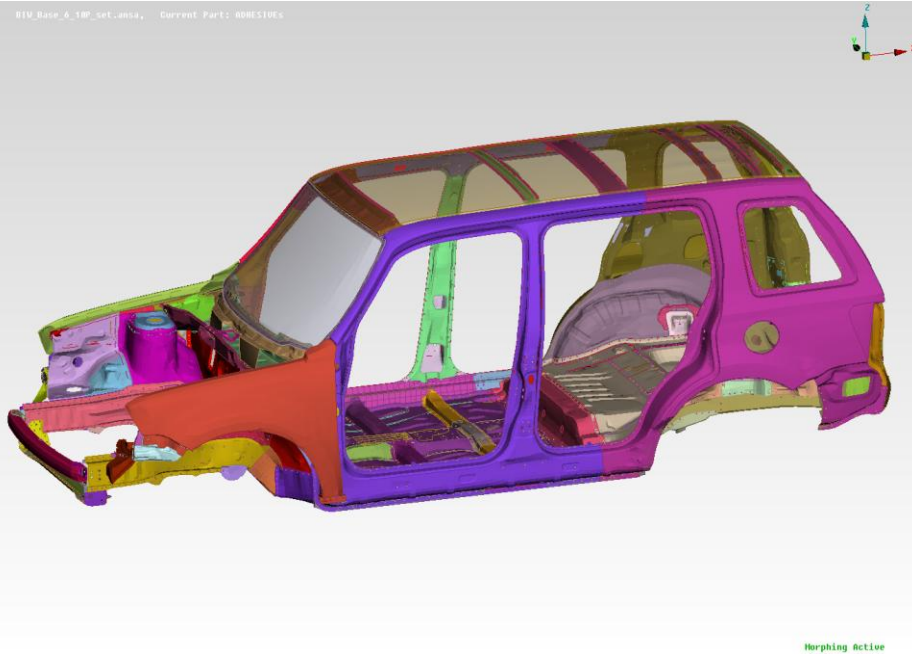
INNERPANEL Point 1875



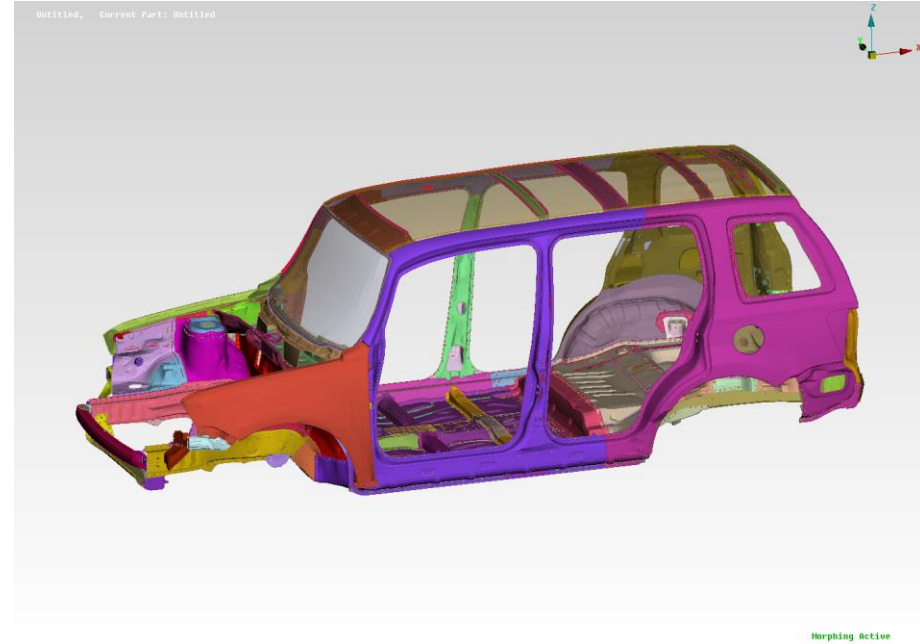
INNERPANEL Point 777



Baseline and Optimal Design



Baseline Design

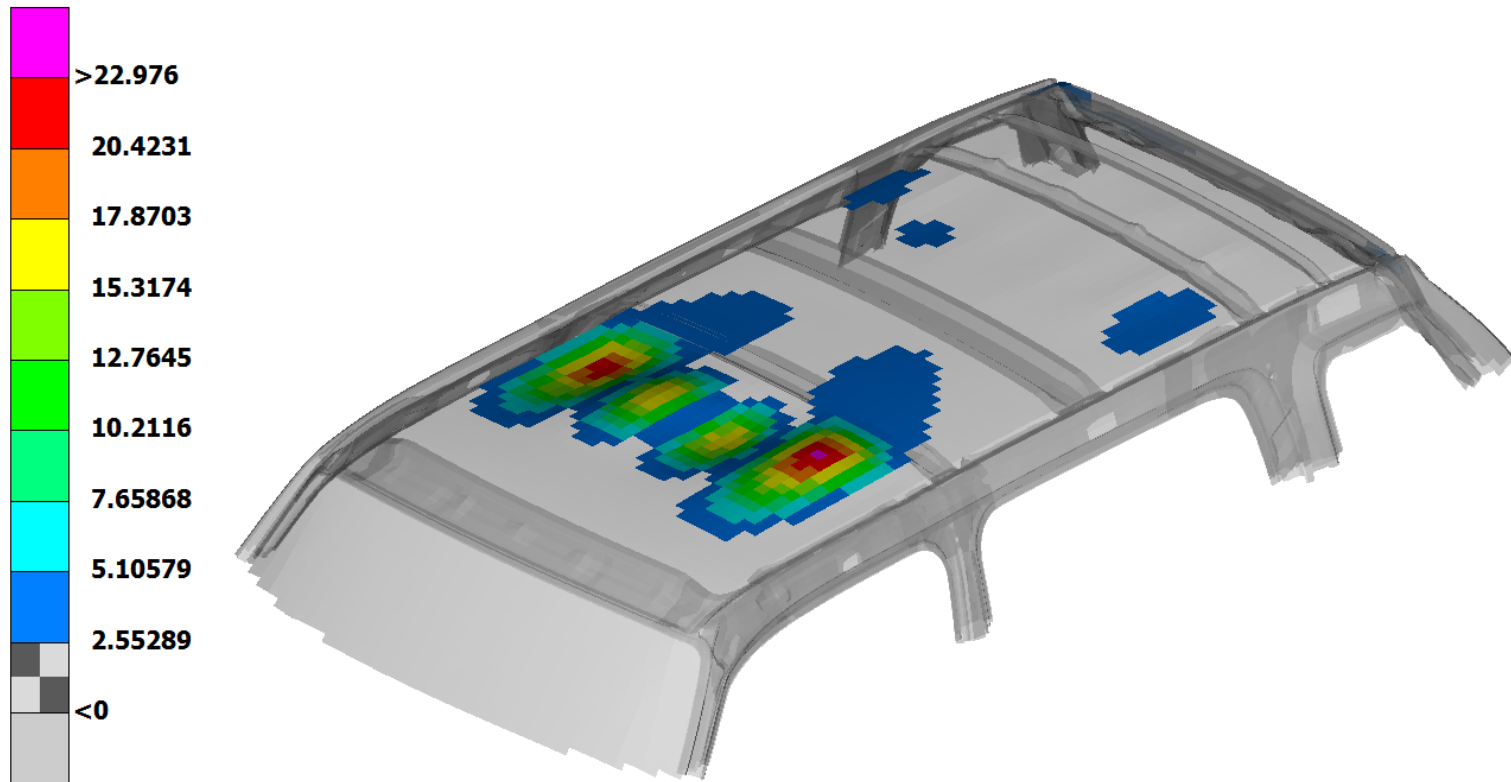


Optimal Design



Roof Response: Baseline at 73 Hz

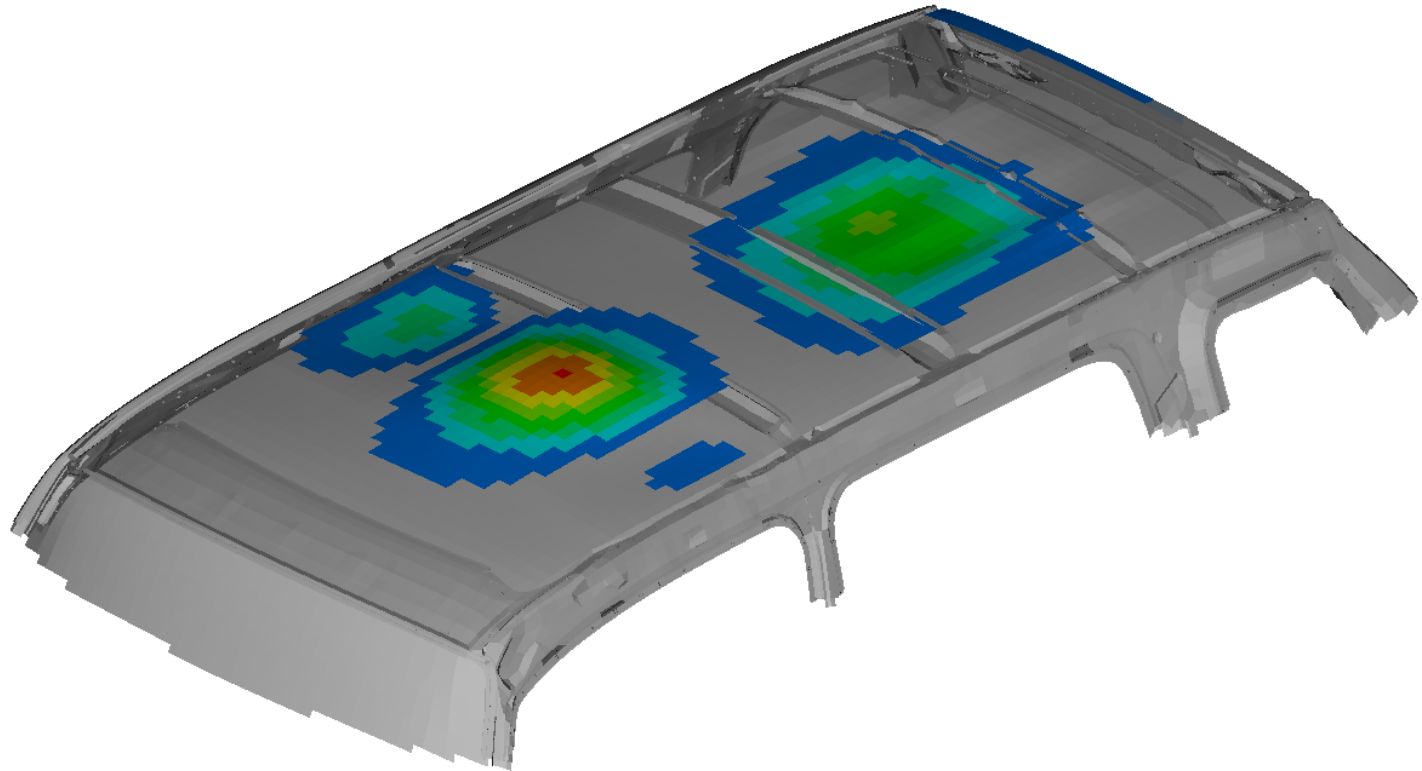
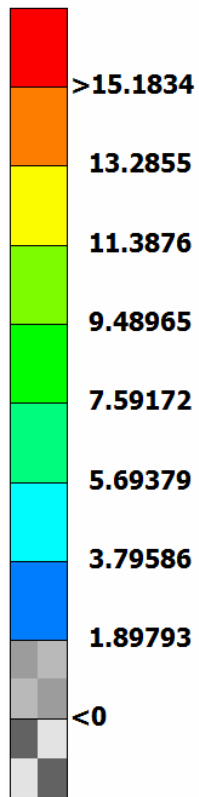
0:base_phi100.op2 : Scalar: Eigenvectors,Translational,Magnitude : : SUBCASE 1 ::MODE 41 ,FREQUENCY 7.296678E+001 ,EIGENVALUE 2.101891E+005





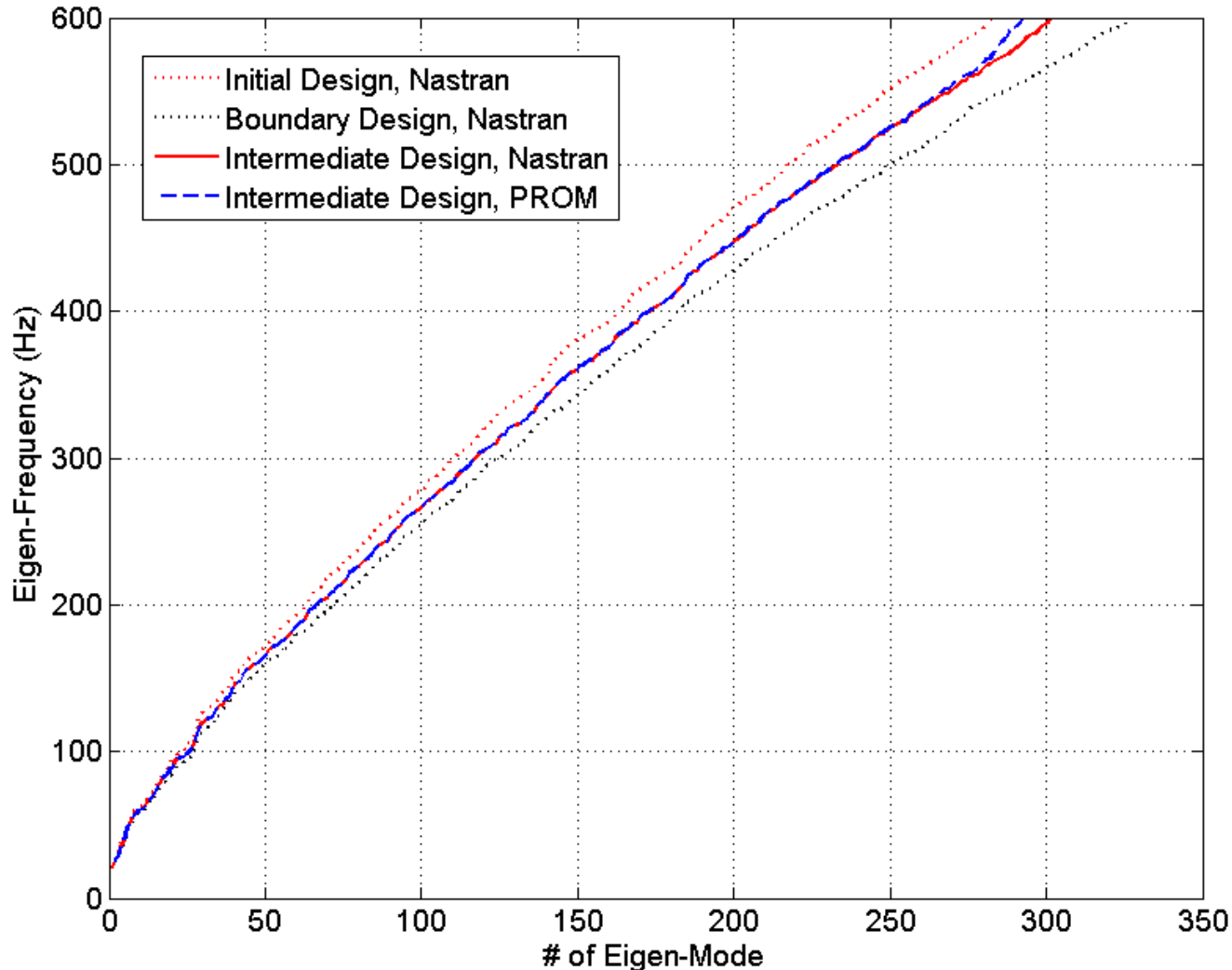
Roof Response: Optimal Design at 72.8 Hz

0:NormalModes.op2 : Scalar: Eigenvectors,Translational,Magnitude : : Scale Factor 2.000E+000 : SUBCASE 1 ::MODE 37 ,FREQUENCY 7.284739E+001 ,EIGENVALUE 2.095018E+005



PROM and MCA for Shape Changes

A Door Example



PROM Re-Analysis

Error less than 0.05%